

# ON THE OUTER COEFFICIENT OF QUASICONFORMALITY OF A CYLINDRICAL MAP OF A CONVEX DIHEDRAL WEDGE

KARI HAG and MARJATTA NÄÄTÄNEN

## 1. Introduction

Let  $D$  and  $D'$  be domains in  $\mathbf{R}^3$  and let  $f: D \rightarrow D'$  be a homeomorphism. With each  $f$  we can associate two numbers, the inner and outer dilatation of  $f$ ,

$$K_I(f) = \sup_{\Gamma} \frac{M(f\Gamma)}{M(\Gamma)}, \quad K_O(f) = \sup_{\Gamma} \frac{M(\Gamma)}{M(f\Gamma)},$$

which measure how far  $f$  is from being conformal. Here  $M(\Gamma)$  and  $M(f\Gamma)$  are the moduli of the curve families  $\Gamma$  and  $f\Gamma$ , the suprema being taken over all families in  $D$ ; see [6]. Further, the inner and outer coefficients of quasiconformality of  $D$  with respect to  $D'$  are defined as

$$K_I(D, D') = \inf_f K_I(f), \quad K_O(D, D') = \inf_f K_O(f).$$

The coefficients of quasiconformality have been calculated only for very few domains. For example, only  $K_O(D, B^3)$  has been determined when  $D$  is an infinite cylinder or an infinite convex cone. On the other hand, only  $K_I(D, B^3)$  is known when  $D$  is a convex dihedral wedge. More precisely, Gehring and Väisälä ([3], [6; p. 134]) have found that  $K_I(D, D') = \beta/\alpha$  in the case of convex dihedral wedges with angles  $\alpha, \beta$  and  $\alpha \leq \beta$ . It is claimed by Syčev [4] that also  $K_O(D, D') = \beta/\alpha$ , but no proof is given. In Section 3 we show that this result follows easily for a subclass of mappings which satisfy a cylindrical condition; see 2.1. Taari [5] has obtained the same result for a subclass of mappings satisfying two local conditions; see 4.1. In Section 4 we use a mapping  $f$  satisfying Taari's conditions to get a cylindrical map  $h$  with  $K_O(f) \cong K_O(h)$ . Hence Taari's result follows from our simpler argument.

## 2. Basic notation

2.1. *Definitions.* Let  $(t, \psi, \varphi)$  be spherical coordinates in  $\mathbf{R}^3$ , where the polar angle  $\varphi$  is measured from the positive  $x_3$ -axis. A domain in  $\mathbf{R}^3$  is a *convex dihedral wedge* of angle  $\alpha$ ,  $0 < \alpha \leq \pi$ , if it can be mapped by a similarity transformation onto the domain  $D_\alpha = \{(t, \psi, \varphi) | t > 0, 0 < \psi < \alpha, 0 < \varphi < \pi\}$ .

Let  $F$  denote the class of homeomorphisms  $f: \bar{D}_\alpha \rightarrow \bar{D}_\pi$ ,  $0 < \alpha \leq \pi$ , whose restrictions  $f|_{D_\alpha}: D_\alpha \rightarrow D_\pi$  are quasiconformal, and for sufficiently small radii map the intersection of  $D_\alpha$  and a circular infinite cylinder with axis the  $x_3$ -axis onto the intersection of  $D_\pi$  and a similar cylinder. We call such a mapping  $f \in F$  *cylindrical*.

Let  $F_L$  denote the class of homeomorphisms  $f: \bar{D}_\alpha \rightarrow \bar{D}_\pi$ ,  $0 < \alpha \leq \pi$ , whose restrictions  $f|_{D_\alpha}: D_\alpha \rightarrow D_\pi$  are quasiconformal,  $f(0) = 0$ , and which satisfy the following condition at the origin:

$$\lim_{\substack{\delta_1 \rightarrow 0 \\ \delta_2 \rightarrow 0}} \max r'(x) / \min r'(x) = 1,$$

where  $(r', \psi', z') = f(r, \psi, z)$  in terms of cylindrical coordinates, and the maximum and minimum are taken over  $x \in S(\delta_1, \delta_2) = \{(r, \psi, z) | r = \delta_1, |z| \leq \delta_2\} \cap \bar{D}_\alpha$ . We call such a mapping  $f \in F_L$  *cylindrical at the origin*.

2.2. Remark. We can state the definitions for closures of wedges without loss of generality since every cylindrical quasiconformal mapping  $f: D_\alpha \rightarrow D_\pi$ ,  $0 < \alpha \leq \pi$ , can be extended to a homeomorphism  $f^*: \bar{D}_\alpha \rightarrow \bar{D}_\pi$ , such that  $f^*(x) \rightarrow \infty$  as  $x \rightarrow \infty$ .

### 3. The outer coefficient for cylindrical mappings

3.1. Theorem. For the class  $F$  of cylindrical mappings

$$\inf \{K_O(f) | f \in F\} = \pi/\alpha.$$

*Proof.* We show first that  $K_O(f) \geq \pi/\alpha$  for  $f \in F$ . Using cylindrical coordinates, let  $r_2 > r_1$  and  $G_i = \{(r, \psi, z) | 0 < r < r_i, 0 < \psi < \alpha, z_1 < z < z_2\}$  for  $i = 1, 2$ , and let  $\Gamma$  be the family of curves joining the set  $\{(r, \psi, z) | r_1 \leq r \leq r_2, \psi = 0, z_1 \leq z \leq z_2\}$  to a similar set with  $\psi = \alpha$ , in the closure of  $G_2 - G_1$ . Then as in Gehring [2; Lemma 1],

$$(1) \quad M(\Gamma) = (r_1^{-1} - r_2^{-1})(z_2 - z_1)\alpha^{-2}.$$

Let  $\Gamma_1$  be the family of curves joining the sets  $\bar{G}_1 \cap \{(r, \psi, z) | z = z_i\}$ ,  $i = 1, 2$ , in  $\bar{G}_1$ . Then by Väisälä [6; 7.2],

$$(2) \quad M(\Gamma_1) = \alpha \pi r_1^2 / (2\pi(z_2 - z_1)^2).$$

By (1) and (2),

$$(3) \quad M(\Gamma)^2 M(\Gamma_1) = \frac{1}{2} \alpha^{-3} (1 - r_1/r_2)^2.$$

Let  $r'_i$  be the radius of  $f(G_i)$ ,  $i = 1, 2$ , and let  $\bar{z}_i$  and  $\underline{z}_i$  be the maximal and minimal  $z$ -coordinates in the  $f$ -image of the set  $\bar{G}_2 \cap \{(r, \psi, z) | z = z_i\}$   $i = 1, 2$ , respectively. Denote by  $\Gamma'$  and  $\Gamma'_1$  the images of  $\Gamma$  and  $\Gamma_1$  under  $f$ . Then

$$M(\Gamma') \leq (1/r'_1 - 1/r'_2)(\bar{z}_2 - \underline{z}_1)\pi^{-2},$$

$$M(\Gamma'_1) \leq \frac{1}{2} \pi (r'_1)^2 (\underline{z}_2 - \bar{z}_1)^{-2},$$

and

$$(4) \quad M(\Gamma')^2 M(\Gamma'_1) \cong \frac{1}{2} \pi^{-3} (1 - r'_1/r'_2)^2 (\bar{z}_2 - \bar{z}_1)^2 (z_2 - \bar{z}_1)^{-2}.$$

Next we consider  $\bar{z}_2 - \bar{z}_2$ . We extend  $f$  to a quasiconformal mapping  $\hat{f}$  of  $\mathbf{R}^3$  using the same foldings as Taari [5]: Let  $g: D_\alpha \rightarrow D_\pi$  denote the folding given by  $g(r, \psi, z) = (r, \pi\psi/\alpha, z)$ . Next we extend  $f \circ g^{-1}: D_\pi \rightarrow D_\pi$  to a quasiconformal mapping  $f_1: \mathbf{R}^3 \rightarrow \mathbf{R}^3$  by reflection. Finally, let  $f_2: \mathbf{R}^3 \rightarrow \mathbf{R}^3$  be  $f_2(r, \psi, z) = (r, \psi', z)$ , where

$$\psi' = \begin{cases} \alpha\psi/\pi & \text{for } 0 \leq \psi \leq \pi \\ \alpha + (2\pi - \alpha)\pi^{-1}(\psi - \pi) & \text{for } \pi \leq \psi \leq 2\pi. \end{cases}$$

Then  $\hat{f} = f_1 \circ f_2^{-1}: \mathbf{R}^3 \rightarrow \mathbf{R}^3$  is quasiconformal and  $\hat{f}|_{\bar{D}_\alpha} = f$ . Lemma 8.1 of [3] applies to  $\hat{f}^{-1}|\{(r, \psi, z) | 0 < r < r'_2\}$  followed by the map  $h(r, \psi, z) = (t, \psi, \varphi)$  with  $t = e^z$ ,  $\varphi = \pi r / (2r_2)$ . (We can assume  $f$  to be normalized in such a way that  $f(0, 0, z) \rightarrow +\infty$  as  $z \rightarrow +\infty$ .) We get

$$(5) \quad 0 \leq \bar{z}_2 - \bar{z}_2 \leq r'_2 AK_I (h \circ \hat{f}^{-1}),$$

where  $A$  is an absolute constant.

On the other hand, by (3) and (4),

$$\alpha^{-3} (1 - r_1/r_2)^2 \leq K_O(f)^3 \pi^{-3} (\bar{z}_2 - \bar{z}_1)^2 (z_2 - \bar{z}_1)^{-2}.$$

Letting  $z_2 \rightarrow \infty$  we get by (5)

$$\alpha^{-3} (1 - r_1/r_2)^2 \leq K_O(f)^3 \pi^{-3}.$$

From this with  $r_1 \rightarrow 0$  we see that  $K_O(f) \geq \pi/\alpha$ . On the other hand, if  $f$  is the cylindrical map

$$(6) \quad f(r, \psi, z) = (r, \pi\psi/\alpha, \pi z/\alpha)$$

we have equality so the bound is sharp.

The above result can be extended to locally cylindrical mappings as follows:

3.2. Theorem. For the class  $F_L$  of mappings cylindrical at the origin,

$$\inf \{K_O(f) | f \in F_L\} = \pi/\alpha.$$

*Proof.* Since the mapping (6) is cylindrical at the origin it suffices, by Theorem 3.1, to show that for each  $f \in F_L$  there exists a  $g \in F$  such that  $K_O(f) \cong K_O(g)$ . As in the proof of Theorem 3.1, each  $f \in F_L$  can be extended to a quasiconformal mapping  $\hat{f}: \mathbf{R}^3 \rightarrow \mathbf{R}^3$ . Next, let  $\hat{g}_n: \mathbf{R}^3 \rightarrow \mathbf{R}^3$  be the sequence defined by  $\hat{g}_n(x) = a_n f(x/n)$ , where  $a_n$  is chosen in such a way that  $|\hat{g}_n(e_1)| = 1$ . Since  $\hat{g}_n(0) = 0$  we conclude by [6; 19.4, 20.5] that  $\{\hat{g}_n\}$  is a normal family and there is a subsequence  $\hat{g}_j$ ,  $j \in J \subset \mathbf{N}$ , converging to a limit function  $\hat{g}: \mathbf{R}^3 \rightarrow \mathbf{R}^3$ . The convergence is uniform on compact subsets of  $\mathbf{R}^3$  and  $\hat{g}$  is a homeomorphism since  $\hat{g}(0) = 0$ ,  $|\hat{g}(e_1)| = 1$ ; see [6; 21.3]. By [6; 37.2]  $\hat{g}$  is quasiconformal,  $\hat{g}(D_\alpha) = D_\pi$ , and  $K_O(f) \cong K_O(g)$ ,

where  $g = \hat{g}|_{\bar{D}_\alpha}$ . It follows that for each  $r_0 > 0$   $g$  maps the compact sets  $\{(r, \psi, z) | r = r_0, |z| \leq M\} \cap \bar{D}_\alpha$  into some cylindrical surface. Also,  $g(0) = 0$  and, by a simple topological argument,  $g \in F$ .

3.3. Remark. So far we have only considered the problem of determining  $K_O(D_\alpha, D_\beta)$ ,  $0 < \alpha \leq \beta < \pi$ , for  $\beta = \pi$ . Composing  $f: D_\alpha \rightarrow D_\beta$  with the standard folding (6),  $\alpha$  replaced by  $\beta$ , we deduce that  $K_O(D_\alpha, D_\beta) = \beta/\alpha$ .

#### 4. Application

As an application we construct in Theorem 4.3 a cylindrical map  $h$  from Taari's functions and show that Taari's result follows from our result.

4.1. *Taari's conditions.* Taari [5] considers the subclass of homeomorphisms  $f: \bar{D}_\alpha \rightarrow \bar{D}_\pi$ ,  $0 < \alpha \leq \pi$ ,  $f(0) = 0$ , whose restrictions  $f|_{D_\alpha}$  are quasiconformal mappings onto  $D_\pi$  and which satisfy the following conditions at the origin:

*Condition A.* There is a polar angle  $\varphi_0$ ,  $0 < \varphi_0 < \pi/2$  such that the limit

$$\lim_{t \rightarrow 0^+} f(te)/t = k(e) \neq 0, \infty$$

exists for every  $e \in \bar{D}_\alpha$  with  $0 \leq (e, e_3) \leq \varphi_0$ , where  $(e, e_3)$  denotes the acute angle between the vectors  $e$  and  $e_3$ .

*Condition B.* For  $e \in \bar{D}_\alpha$

$$\lim_{\varepsilon \rightarrow 0^+} \max(k(e), k(e_3)) / \min(k(e), k(e_3)) = 1,$$

where the maximum and minimum are over all vectors  $e$  such that  $(e, e_3) = \varepsilon$ .

4.2. Theorem. *Let  $f$  be a mapping satisfying Taari's conditions stated in 4.1. Then there is a cylindrical map  $h$  such that  $K_O(f) \cong K_O(h)$ .*

*Proof.* Given  $f$  we construct, stepwise, a map  $\hat{h}: \mathbf{R}^3 \rightarrow \mathbf{R}^3$  whose restriction  $h = \hat{h}|_{\bar{D}_\alpha}$  will be cylindrical and satisfy  $K_O(f) \cong K_O(h)$ .

The first step is carried out in [5]. Using Condition A Taari constructs a mapping  $g: \bar{D}_\alpha \rightarrow \bar{D}_\pi$ ,  $g(0) = 0$ , such that for each  $e \in \bar{D}_\alpha$ ,  $0 \leq (e, e_3) \leq \varphi_0$ , the restriction of  $g$  to the ray  $\{te | t \geq 0\}$  is linear, i.e.  $g(te) = tg(e)$ . Furthermore, using additional rotation and stretching we can assume  $g(e_3) = e_3$ . Also,  $K_O(g) \leq K_O(f)$ .

Next the mapping  $g$  is extended to a quasiconformal map  $\hat{g}: \mathbf{R}^3 \rightarrow \mathbf{R}^3$  as in the proof of Theorem 3.1. We observe, for later use, that if  $0 \leq (e, e_3) \leq \varphi_0$ , the restriction of  $\hat{g}$  to the ray  $\{te | t \geq 0\}$  is linear. Now, let  $T_n$  denote translation by  $ne_3$  and let  $\hat{h}_n = T_{-n} \circ \hat{g} \circ T_n$ . For  $t \geq -n$ ,  $\hat{h}_n(te_3) = T_{-n}(\hat{g}((t+n)e_3)) = te_3$ ; hence  $\{\hat{h}_n\}$  is a normal family and has a subsequence  $\hat{h}_j$ ,  $j \in J \subset \mathbf{N}$ , converging to a quasiconformal mapping  $\hat{h}: \mathbf{R}^3 \rightarrow \mathbf{R}^3$ . The convergence is uniform on compact subsets of  $\mathbf{R}^3$ ,  $\hat{h}(D_\alpha) = D_\pi$  and  $K_O(h) \leq K_O(g)$ , where  $h = \hat{h}|_{\bar{D}_\alpha}$ . Hence  $K_O(h) \leq K_O(f)$ .

To complete the proof we will show that if  $C$  is a circular cylinder (domain) with axis the  $x_3$ -axis, then  $\hat{h}(C)$  is a similar cylinder. For such a cylinder  $C$  let  $C_j$  be the cone determined by the circle  $\partial C \cap \{x|x_3=0\}$  and the point  $(-j)e_3$ , and put  $C'_j = \hat{h}_j(C_j)$ . By Theorem 3 of Gehring [1] we find that  $\hat{h}(C) = \text{Ker } C'_j$  since  $C = \text{Ker } C_j$ . Next we show that  $\text{Ker } C'_j$  is a cylinder, i.e. that if  $x_0 \in \text{Ker } C'_j$ , then  $\{x_0 + te_3 | t \in \mathbf{R}\} \subset \text{Ker } C'_j$ . Let  $(r_0, \psi_0, z_0)$  be the cylindrical coordinates of  $x_0$  and let  $x_0 \in \text{Ker } C'_j$ . Then there exists an  $\varepsilon > 0, \varepsilon < r_0$ , such that the cylindrical neighborhood  $N$  with  $|r - r_0| < \varepsilon, |\psi - \psi_0| < \varepsilon, |z - z_0| < \varepsilon$  is in  $C'_j$  for  $j \geq j_0$ . Next consider  $C'_j$ . For large  $j, \hat{g}$  maps  $C_j + je_3$  in such a way that each ray through the origin is mapped onto a ray through the origin. This means that  $C'_j$  is a union of rays through  $-je_3$ ; in particular, all rays through  $-je_3$  meeting  $N$  are in  $C'_j$ . In the case  $t > 0$  take  $j$  so large that also  $z_0 + j > 0$  and

$$\arctan \frac{r_0 - \varepsilon}{z_0 + j + \varepsilon} \leq \arctan \frac{\varepsilon/2}{t - \varepsilon/2}.$$

Then the cylindrical neighborhood of  $x_0 + te_3$  with  $|r - r_0| < \varepsilon/2, |\psi - \psi_0| < \varepsilon/2, |z - (z_0 + t)| < \varepsilon/2$  is in  $C'_j$ . Hence  $\{x_0 + te_3 | t \geq 0\} \subset \text{Ker } C'_j$ . Similarly,  $\{x_0 + te_3 | t < 0\} \subset \text{Ker } C'_j$ . Finally we use Condition B to show that  $\hat{h}(C)$  is circular with axis the  $x_3$ -axis. Since  $k(e) = g(e)$ , we see by Condition B that for all  $j$

$$\lim_{\delta \rightarrow 0^+} \max (\hat{g}(T_j x), e_3) / \min (\hat{g}(T_j x), e_3) = 1,$$

where maximum and minimum are taken over all  $x$  such that  $(T_j x, e_3) = \delta$ . Let  $r > 0$  and put  $S = \{(r, \psi, z) | r = r_0, z = z_0\}$ . For  $j \geq j_1$  we have by the above

$$(7) \quad \max_{x \in S} (\hat{g}(T_j x), e_3) / \min_{x \in S} (\hat{g}(T_j x), e_3) < 1 + \varepsilon.$$

The continuity of  $\hat{g}$  at  $e_3$ , the linearity of  $\hat{g}$  on rays close to the  $x_3$ -axis, and the fact that  $\hat{g}(e_3) = e_3$  together imply that

$$(8) \quad 1 - \varepsilon < |\hat{g}(x + je_3)| / |x + je_3| < 1 + \varepsilon$$

for  $j \geq j_2, x \in S$ . Suppose that  $j \geq j_1, j_2$  and let  $\underline{\varphi}_j = \min_{x \in S} (\hat{g}(T_j x), e_3), \bar{\varphi}_j = \max_{x \in S} (\hat{g}(T_j x), e_3)$ . By (7)

$$(9) \quad \bar{\varphi}_j < (1 + \varepsilon) \underline{\varphi}_j.$$

From (8) we get for  $x \in S$

$$(10) \quad (1 - \varepsilon) \sqrt{r_0^2 + (z_0 + j)^2} < |\hat{g}(x + je_3)| < (1 + \varepsilon) \sqrt{r_0^2 + (z_0 + j)^2}.$$

Then by (9) and (10)

$$(11) \quad \frac{\max_{x \in S} r(\hat{g}(x + je_3))}{\min_{x \in S} r(\hat{g}(x + je_3))} < \frac{(1 + \varepsilon) \sin(1 + \varepsilon) \underline{\varphi}_j}{(1 - \varepsilon) \sin \underline{\varphi}_j}.$$

Since  $\hat{h}_j(x) = \hat{g}(x + je_3) - je_3$ , we can replace  $r(\hat{g}(x + je_3))$  by  $r(\hat{h}_j(x))$  in (11). Since  $S$  is compact,  $\hat{h}_j \rightarrow \hat{h}$  uniformly on  $S$ . Also,  $\varrho_j \rightarrow 0$  as  $j \rightarrow \infty$ , and the upper bound in (11) can be replaced by  $(1 + \varepsilon)^3 / (1 - \varepsilon)$ . Since  $\varepsilon > 0$  was arbitrary,

$$\max r(\hat{h}(x)) / \min r(\hat{h}(x)) = 1$$

for  $x \in S$ .

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University of Michigan  
 Department of Mathematics  
 Ann Arbor, Michigan 48109  
 USA

University of Trondheim  
 Department of Mathematics, NTH  
 N-7034 Trondheim  
 Norway

University of Helsinki  
 Department of Mathematics  
 SF-00100 Helsinki 10  
 Finland

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