ON PSEUDO-MONOTONE OPERATORS AND NONLINEAR PARABOLIC INITIAL-BOUNDARY VALUE PROBLEMS ON UNBOUNDED DOMAINS

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1. Introduction

Let Ω be an arbitrary domain in \mathbb{R}^N $(N \ge 1)$ and let Q be the cylinder $\Omega \times (0, T)$ with a given T > 0. We shall consider on Q the quasilinear parabolic partial differential operator of order 2m $(m \ge 1)$ of the form

(1)
$$\frac{\partial u(x,t)}{\partial t} + Au(x,t),$$

where A is an elliptic operator given in the divergence form

(2)
$$Au(x,t) = \sum_{|\alpha| \le m} (-1)^{|\alpha|} D^{\alpha} A_{\alpha}(x,t,u,Du,...,D^{m}u).$$

The coefficients A_{α} are regarded as real-valued functions of the point (x, t) in Q, of $\eta = \{\eta_{\beta} : |\beta| \le m-1\}$ in \mathbb{R}^{N_1} and of $\zeta = \{\zeta_{\beta} : |\beta| = m\}$ in \mathbb{R}^{N_2} , where $\alpha = (\alpha_1, ..., \alpha_N)$ and $\beta = (\beta_1, ..., \beta_N)$ are N-tuples of nonnegative integers, $|\beta| = \beta_1 + ... + \beta_N$ and $D^{\alpha} = \prod_{i=1}^{N} (\partial_i \partial x_i)^{\alpha_i}$.

If we assume that the functions A_{α} satisfy the familiar condition

(A₁) Each $A_{\alpha}(x, t, \eta, \zeta)$ is measurable in (x, t) for fixed $\xi = (\eta, \zeta)$ and continuous in ξ for fixed (x, t). For a given p>1 there exists a constant $c_1>0$ and a function $k_1 \in L^{p'}(Q)$ with $p' = p/(p-1)^{-1}$ such that

$$|A_{\alpha}(x, t, \eta, \zeta)| \leq c_1 (|\zeta|^{p-1} + |\eta|^{p-1} + k_1(x, t))$$

for all $|\alpha| \leq m$, all $(x, t) \in Q$ and all $\zeta = (\eta, \zeta) \in \mathbb{R}^{N_1 + N_2} = \mathbb{R}^{N_0}$,

then the operator A gives rise to a bounded map S from the space $\mathscr{V} = L^p(0, T; V)$ to its dual space \mathscr{V}^* , V being a closed subspace of the Sobolev space $W^{m,p}(\Omega)$.

When Ω is a bounded domain, the operator $\partial/\partial t$ induces a maximal monotone map L from the subset $D(L) = \{v \in \mathscr{V}: \partial v/\partial t \in \mathscr{V}^*, v(x, 0) = 0 \text{ in } \Omega\}$ to \mathscr{V}^* , and

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from a simple set of additional hypotheses of the Leray—Lions type it can be derived that S is pseudo-monotone on D(L). This result is then applicable to the existence of weak solutions for the parabolic initial-boundary value problems for the operator (1).

When Ω is unbounded, the situation is different while the compactness part of the Sobolev embedding theorem and Relich's selection theorem are no more available and the above definition of the set D(L) does not make sense.

The purpose of the present note is to show, for arbitrary domains Ω , that the map S induced by the elliptic operator A is pseudo-monotone as a map from the space $\mathscr{W} = \mathscr{V} \cap L^2(Q)$ to \mathscr{W}^* on the set $D(L) = \{v \in \mathscr{W} : \frac{\partial v}{\partial t} \in \mathscr{W}^*, v(x, 0) = 0 \text{ in } \Omega\}$ whenever the coefficients A_{α} satisfy the following conditions (cf. [5] p. 323, [6]) in addition to (A_1) :

(A₂) For each $(x, t) \in Q$, each $\eta \in \mathbb{R}^{N_1}$ and any pair of distinct elements ζ and ζ^* in \mathbb{R}^{N_2} ,

$$\sum_{|\alpha|=m} \{A_{\alpha}(x, t, \eta, \zeta) - A_{\alpha}(x, t, \eta, \zeta^*)\}(\zeta_{\alpha} - \zeta_{\alpha}^*) > 0.$$

(A₃) There exist a constant $c_2 > 0$ and functions $k_2 \in L^1(Q)$, $h_{\alpha} \in L^{p'}(Q)$ for all $|\alpha| \leq m$, such that

$$\sum_{|\alpha| \le m} A_{\alpha}(x, t, \xi) \xi_{\alpha} \ge -\sum_{|\alpha| \le m} h_{\alpha}(x, t) \xi_{\alpha} - k_{2}(x, t)$$

for all $(x, t) \in Q$ and all $\xi \in \mathbb{R}^{N_0}$.

This result is analogous to the elliptic case studied by F. E. Browder [1]. In fact, our method here is a modification of the method introduced by R. Landes and V. Mustonen [4], which makes it possible to relax one of the classical conditions imposed on the coefficients A_{α} .

The result of pseudo-monotonicity can be applied to the variational problems for the operator (1) involving a domain which is not necessarily bounded. As an example we shall show that the partial differential equation

(3)
$$\frac{\partial u}{\partial t} + Au = f \quad \text{in} \quad Q$$

with the initial-boundary conditions

(4)
$$\begin{cases} u(x,0) = 0 & \text{in } \Omega \\ D^{\alpha}u = 0 & \text{on } \partial\Omega \times (0,T) & \text{for } |\alpha| \leq m-1 \end{cases}$$

admits a solution u for any given f in $L^{p'}(Q)$. Under similar conditions (a condition stronger than our (A₃) was needed) this existence theorem was also proved by G. Mahler [6] by an ad hoc approximation method which was originally introduced by P. Hess [2] for elliptic Dirichlet problems.

2. Prerequisites

Let Ω be an open subset of \mathbb{R}^N . The Sobolev space of functions u such that u and its distributional derivatives $D^{\alpha}u$ lie in $L^p(\Omega)$ for all $|\alpha| \leq m$ is denoted by $W^{m,p}(\Omega)$. By $W^{m,p}_0(\Omega)$ we mean the closure in $W^{m,p}(\Omega)$ of $C_0^{\infty}(\Omega)$, the space of test functions with compact support in Ω . If $u \in W^{m,p}(\Omega)$, we shall write $\eta(u) = \{D^{\alpha}u: |\alpha| \leq m-1\}, \zeta(u) = \{D^{\alpha}u: |\alpha| = m\}$ and $\zeta(u) = \{D^{\alpha}u: |\alpha| \leq m\}$. When T > 0 is given and V is a closed subspace of the Sobolev space $W^{m,p}(\Omega)$, we denote $\mathscr{V} = L^p(0, T; V)$, a Banach space equipped with the norm

$$\|u\|_{\mathscr{V}} = \left\{\int_{0}^{T} \|u(t)\|_{V}^{p} dt\right\}^{1/p}$$

We let further \mathscr{W} stand for the Banach space $\mathscr{V} \cap L^2(Q)$ with $Q = \Omega \times (0, T)$ and with the norm $\|\cdot\|_{\mathscr{W}} = \|\cdot\|_{\mathscr{V}} + \|\cdot\|_{L^2(Q)}$.

The duality pairing between the elements u in a Banach space X and f in X^* is denoted by $(f, u)_X$, where the subscript X will be omitted when no confusion is possible. If $1 , <math>\mathcal{W}$ is reflexive and its dual space is $\mathcal{W}^* = \mathcal{V}^* + L^2(Q)$, where $\mathcal{V}^* = L^{p'}(0, T; V^*)$. Furthermore,

$$\mathscr{W} \subset L^2(Q) \subset \mathscr{W}^* \subset L^1(0, T; V^* + L^2(\Omega));$$

for each $u \in \mathcal{W}$ the distribution derivative $u' = \partial u/\partial t$ can be defined and the condition $u' \in \mathcal{W}^*$ makes sense. Each $u \in \mathcal{W}$ with $u' \in \mathcal{W}^*$ is (after a modification on a set of measure zero) a continuous function, $[0, T] \rightarrow L^2(\Omega)$ and the following integration formula holds (see [6], [7]) for all $u, v \in \mathcal{W}$ with $u', v' \in \mathcal{W}^*$:

(5)
$$(u', v)_{\mathscr{W}} + (v', u)_{\mathscr{W}} = (u(T), v(T))_{L^2(\Omega)} - (u(0), v(0))_{L^2(\Omega)}.$$

Let L stand for the linear map from \mathscr{W} to \mathscr{W}^* which takes u to u' having the domain

$$D(L) = \{ u \in \mathcal{W} \colon u' \in \mathcal{W}^*, \ u(x, 0) = 0 \text{ in } \Omega \}.$$

It follows from (5) that $(Lu, u) \ge 0$ for all $u \in D(L)$. Thus L is a monotone linear map.

We close this section by recalling the definition of a pseudo-monotone map and an abstract surjectivity result which we will employ in proving the existence theorem in Section 4. Indeed, Theorem 1.2 of [5] p. 319 can be stated as follows:

Proposition 1. Let X be a reflexive Banach space with strictly convex norms in X and X^{*}. Let L be a linear maximal monotone map from D(L) to X^{*} with D(L)dense in X, let T be a bounded map from X to X^{*}, and suppose that T is D(L)-pseudomonotone, i.e. for any sequence $(v_n) \subset D(L)$ with $v_n \rightarrow v$ (weak convergence) in X, $Lv_n \rightarrow Lv$ in X^{*} and $\limsup (T(v_n), v_n - v) \leq 0$, it follows that $T(v_n) \rightarrow T(v)$ in X^{*} and $(T(v_n), v_n) \rightarrow (T(v), v)$. If T is coercive on X, i.e. $(T(u), u) ||u||^{-1} \rightarrow \infty$ as $||u|| \rightarrow \infty$ in X, then for any $f \in X^*$ there is $u \in D(L)$ such that Lu + T(u) = f.

3. Theorem on pseudo-monotonicity

Let us assume that the coefficients A_{α} of the operator (2) satisfy the conditions (A₁), (A₂) and (A₃) in the given domain $Q = \Omega \times (0, T)$. On account of (A₁) the equation

(6)
$$a(u,v) = \sum_{|\alpha| \le m} \int_{Q} A_{\alpha}(x,t,\xi(u)) D^{\alpha}v \, dx \, dt$$

defines a bounded semilinear form on $\mathscr{V} \times \mathscr{V}$. Hence (6) gives rise to a bounded (nonlinear) map S from \mathscr{V} to \mathscr{V}^* by the rule

(7)
$$(S(u), v) = a(u, v), \quad u, v \in \mathscr{V}.$$

In view of (A_1) and (A_3) it is clear that \mathscr{V} would be the natural space for the mapping S but, on the other hand, the map L is defined on the subset $D(L) \subset \mathscr{W} \subset \mathscr{V}$ only, with values in \mathscr{W}^* . Therefore we shall regard S as a map from \mathscr{W} to \mathscr{W}^* and prove

Theorem 1. Let Ω be an arbitrary domain in \mathbb{R}^N , T>0, $Q=\Omega\times(0, T)$ and let the functions A_{α} satisfy the conditions (A_1) , (A_2) and (A_3) . Then the map S from \mathcal{W} to \mathcal{W}^* defined by (7) is D(L)-pseudo-monotone.

Proof. We can follow the lines of the proof of the elliptic case in [4]. Indeed, let $(v_n) \subset D(L)$ be a sequence such that $v_n \rightarrow v$ in \mathcal{W} , $Lv_n \rightarrow Lv$ in \mathcal{W}^* and lim sup $(S(v_n), v_n - v) \equiv 0$. We must verify that $S(v_n) \rightarrow S(v)$ in \mathcal{W}^* and that $(S(v_n), v_n) \rightarrow (S(v), v)$, at least for an infinite subsequence of (v_n) . As $v_n \rightarrow v$ in \mathcal{W} , $D^{\alpha}v_n \rightarrow D^{\alpha}v$ in $L^p(Q)$ for all $|\alpha| \equiv m$ and $v_n \rightarrow v$ in $L^2(Q)$. Our aim is to show that $D^{\alpha}v_n(x, t) \rightarrow D^{\alpha}v(x, t)$ almost everywhere in Q for all $|\alpha| \equiv m$ for some subsequence. By (A_1) this implies that $A_{\alpha}(x, t, \xi(v_n)) \rightarrow A_{\alpha}(x, t, \xi(v))$ a.e. in Q for all $|\alpha| \equiv m$. By (A_1) this also means that $A_{\alpha}(\ldots, \xi(v_n)) \rightarrow A_{\alpha}(\ldots, \xi(v))$ in $L^{p'}(Q)$, and thus $S(v_n) \rightarrow S(v)$ in \mathcal{W}^* follows. The a.e. convergence of $D^{\alpha}v_n(x, t)$ to $D^{\alpha}v(x, t)$ for all $|\alpha| \equiv m-1$ is established by Aubin's Lemma ([5] p. 57). Indeed, $W^{m,p}(\Omega)$ is compactly embedded in $W^{m-1,p}(\omega)$ for any subdomain ω with a compact closure in Ω . Thus $v_n \rightarrow v$ in \mathcal{W} and $Lv_n \rightarrow Lv$ in \mathcal{W}^* together imply (cf. [6] p. 205) that $v_n \rightarrow v$ (strongly) in $L^p(0, T; W^{m-1,p}(\omega))$, i.e. $D^{\alpha}v_n \rightarrow D^{\alpha}v$ in $L^p(\omega \times (0, T))$ for all $|\alpha| \equiv m-1$, and the a.e. convergence for a subsequence follows.

To verify that $D^{\alpha}v_n(x,t) \rightarrow D^{\alpha}v(x,t)$ a.e. in Q also for all $|\alpha|=m$ we denote

$$q_{n}(x, t) = \sum_{|\alpha|=m} \{A_{\alpha}(x, t, \eta(v_{n}), \zeta(v_{n})) - A_{\alpha}(x, t, \eta(v_{n}), \zeta(v))\}(D^{\alpha}v_{n} - D^{\alpha}v),$$

$$p_{n}(x, t) = \sum_{|\alpha|=m} A_{\alpha}(x, t, \xi(v_{n}))(D^{\alpha}v_{n} - D^{\alpha}v),$$

$$r_{n}(x, t) = \sum_{|\alpha|=m} A_{\alpha}(x, t, \eta(v_{n}), \zeta(v))(D^{\alpha}v - D^{\alpha}v_{n}),$$

$$s_{n}(x, t) = \sum_{|\alpha|=m-1} A_{\alpha}(x, t, \xi(v_{n}))(D^{\alpha}v - D^{\alpha}v_{n}).$$

Then $q_n = p_n + r_n + s_n$ in Q. If we can show that $q_n(x, t) \rightarrow 0$ a.e. in Q, then the desired result follows from Lemma 6 due to R. Landes [3]. In fact, as $q_n(x, t) \ge 0$ for almost all $(x, t) \in Q$ by (A₂), it suffices to show that

(8)
$$\limsup \int_{Q_k} q_n(x, t) \, dx \, dt \leq \varepsilon_k,$$

where $Q_k = \Omega_k \times (0, T)$, (Ω_k) is a growing sequence of bounded subdomains of Ω such that $\mu(\Omega \setminus \bigcup_{k=1}^{\infty} \Omega_k) = 0$ and $\varepsilon_k \to 0$ as $k \to \infty$. For any fixed k we have

$$\int_{Q_k} q_n(x, t) = \int_{Q} p_n(x, t) - \int_{Q \setminus Q_k} p_n(x, t) + \int_{Q_k} (r_n(x, t) + s_n(x, t)),$$

where we know by assumption that $\limsup \int_Q p_n(x, t) \leq 0$. Moreover, since $(D^{\alpha}v_n)$ is bounded in $L^p(Q)$ and $(A_{\alpha}(.,., \xi(v_n)))$ is bounded in $L^{p'}(Q)$, we get by (A₃),

$$-\int_{Q\smallsetminus Q_{k}} p_{n}(x,t) = -\sum_{|\alpha| \leq m} \int_{Q\smallsetminus Q_{k}} A_{\alpha}(x,t,\xi(v_{n})) D^{\alpha} v_{n}$$
$$+ \sum_{|\alpha| \leq m} \int_{Q\smallsetminus Q_{k}} A_{\alpha}(x,t,\xi(v_{n})) D^{\alpha} v$$
$$\leq c \sum_{|\alpha| \leq m} \left\{ \int_{Q\smallsetminus Q_{k}} |h_{\alpha}(x,t)|^{p'} \right\}^{1/p'} + \int_{Q\smallsetminus Q_{k}} k_{2}(x,t)$$
$$+ c \sum_{|\alpha| \leq m} \left\{ \int_{Q\smallsetminus Q_{k}} |D^{\alpha}v|^{p} \right\}^{1/p} := \varepsilon_{k},$$

where obviously $\varepsilon_k \to 0$ as $k \to \infty$, c being some positive constant. Since $D^{\alpha}v_n \to D^{\alpha}v$ in $L^p(Q_k)$ for all $|\alpha| \leq m-1$ and since $A_{\alpha}(..., \eta(v_n), \zeta(v)) \to A_{\alpha}(..., \eta(v), \zeta(v))$ in $L^{p'}(Q_k)$ for all $|\alpha| = m$ by (A_1) and the dominated convergence theorem, we can conclude that

$$\limsup_{Q_k} \int_{Q_k} \left(r_n(x, t) + s_n(x, t) \right) \leq 0$$

for any fixed k. Thus (8) has been verified.

We complete the proof by showing that $(S(v_n), v_n) \rightarrow (S(v), v)$. In view of the assumption, $\limsup (S(v_n), v_n) \leq (S(v), v)$. Hence it suffices to prove that

(9) $\liminf (S(v_n), v_n) \ge (S(v), v).$

By (A_2) we have

$$\sum_{|\alpha|=m} A_{\alpha}(x, t, \xi(v_n)) D^{\alpha} v_n \ge \sum_{|\alpha|=m} A_{\alpha}(x, t, \eta(v_n), \zeta(v)) (D^{\alpha} v_n - D^{\alpha} v)$$
$$+ \sum_{|\alpha|=m} A_{\alpha}(x, t, \zeta(v_n)) D^{\alpha} v,$$

and hence we get further for any fixed k,

$$\begin{split} \sum_{|\alpha| \leq m} \int_{Q} A_{\alpha}(x, t, \xi(v_n)) D^{\alpha} v_n &\geq \sum_{|\alpha| = m} \int_{Q_k} A_{\alpha}(x, t, \eta(v_n), \zeta(v)) (D^{\alpha} v_n - D^{\alpha} v) \\ &+ \sum_{|\alpha| = m} \int_{Q_k} A_{\alpha}(x, t, \xi(v_n)) D^{\alpha} v + \sum_{|\alpha| \leq m-1} \int_{Q_k} A_{\alpha}(x, t, \xi(v_n)) D^{\alpha} v_n \\ &+ \sum_{|\alpha| \leq m} \int_{Q \setminus Q_k} A_{\alpha}(x, t, \xi(v_n)) D^{\alpha} v_n. \end{split}$$

By the same arguments as above in proving (8) we obtain

$$\liminf \sum_{|\alpha| \leq m} \int_{Q} A_{\alpha}(x, t, \xi(v_n)) D^{\alpha} v_n \geq \sum_{|\alpha| \leq m} \int_{Q} A_{\alpha}(x, t, \xi(v)) D^{\alpha} v - \varepsilon_k,$$

where $\varepsilon_k \rightarrow 0$ as $k \rightarrow \infty$, and so the proof is complete.

4. Parabolic initial-boundary value problem

We shall employ Theorem 1 and Proposition 1 for obtaining an existence theorem for the parabolic equation (3) with initial-boundary conditions (4). Indeed, we can choose $V = W_0^{m,p}(\Omega)$ to obtain

Theorem 2. Let Ω be an arbitrary domain in \mathbb{R}^N , T>0, $Q=\Omega\times(0, T)$ and let the functions A_{α} satisfy the conditions (A_1) , (A_2) and (A_3) . If $a(u, u)||u||_{\varphi}^{-1} \to \infty$ for all $u \in \mathscr{V}$ with $||u||_{\varphi} \to \infty$, then for any $f \in L^{p'}(Q) + L^2(Q)$ the equation (3) admits a weak solution u in D(L), i.e. there exists $u \in D(L)$ such that

(10)
$$\left(\frac{\partial u}{\partial t}, w\right)_{\mathcal{W}} + a(u, w) = (f, w)_{\mathcal{W}} \text{ for all } w \in \mathcal{W}.$$

Proof. First we remark that by assumption the map S defined by (6) is coercive on \mathscr{V} , although not necessarily on \mathscr{W} . Therefore, to invoke Proposition 1 with $X=\mathscr{W}$ we perform the substitution $u=e^{kt}v$ with k a positive constant, as suggested in [6]. Then we obtain from (3) the equation

$$\frac{\partial v}{\partial t} + \tilde{A}v + kv = \tilde{f} \quad \text{in} \quad Q$$

with the initial-boundary conditions (4), where

$$\begin{split} \widetilde{A}v(x,t) &= \sum_{|\alpha| \leq m} (-1)^{|\alpha|} D^{\alpha} \widetilde{A}_{\alpha}(x,t,\xi(v)), \\ \widetilde{A}_{\alpha}(x,t,\xi) &= e^{-kt} A_{\alpha}(x,t,e^{kt}\xi) \quad \text{and} \quad \widetilde{f} = e^{-kt} f. \end{split}$$

It is obvious that the functions \tilde{A}_{α} also satisfy the conditions (A₁) to (A₃) with a new constant \bar{c}_1 and new functions $\bar{h}_{\alpha} \in L^{p'}(Q)$. Now we define a map

$$S_1 = \tilde{S} + S_0 \colon \mathscr{W} \to \mathscr{W}^*$$

by

$$(\tilde{S}(v), w) = \tilde{a}(v, w) = \sum_{|\alpha| \le m} \int_{Q} \tilde{A}_{\alpha}(x, t, \zeta(v)) D^{\alpha} w \, dx \, dt$$

and

$$(S_0(v), w) = k \int_Q v w \, dx \, dt.$$

On account of Theorem 1, \tilde{S} is D(L)-pseudo-monotone. It is easily seen that also the sum $S_1 = \tilde{S} + S_0$ is D(L)-pseudo-monotone. Moreover, S_1 is coercive on \mathcal{W} . Indeed, by the assumption of the theorem, $a(v, v) ||v||_{\mathcal{V}}^{-1} \to \infty$ and therefore

$$\frac{(S_1(v), v)}{\|v\|_{\mathscr{W}}} = \frac{\tilde{a}(v, v) + k \|v\|_{L^2(Q)}}{\|v\|_{\mathscr{V}} + \|v\|_{L^2(Q)}} \to \infty \quad \text{as} \quad \|v\|_{\mathscr{W}} \to \infty.$$

For applying Proposition 1 we must finally verify that the map $L=\partial/\partial t$: $D(L) \rightarrow \mathcal{W}^*$ is maximal monotone and that D(L) is dense in \mathcal{W} . By Lemma 1.2 of [5] p. 313 it suffices to show that for any $v \in \mathcal{W}$ and $w \in \mathcal{W}^*$ such that

(11)
$$0 \le (w - Lu, v - u) \text{ for all } u \in D(L)$$

it follows that $v \in D(L)$ and w = Lv. To show this let $v \in \mathcal{W}$ and $w \in \mathcal{W}^*$ be given, let $\varphi \in C_0^{\infty}(0, T)$ and $\bar{u} \in V \cap L^2(\Omega)$ be arbitrary and let $u = \varphi \bar{u}$. Then $u \in \mathcal{W}$, u(0) = u(T) = 0, $u' = \varphi' \bar{u} \in L^2(Q) \subset \mathcal{W}^*$ and hence $u \in D(L)$. Since (Lu, u) = 0, we get from (11) by (5)

$$0 \leq (w, v) - (\varphi' \bar{u}, v) - (w, \varphi \bar{u}),$$

where

$$(\varphi'\bar{u}, v) = \left(\int_{0}^{T} \varphi'(t)v(t) dt, \bar{u}\right)_{V \cap L^{2}(\Omega)}$$

and

$$(w, \, \varphi \bar{u}) = \left(\int_0^T \varphi(t) \, w(t) \, dt, \, \bar{u} \right)_{V \,\cap \, L^2(\Omega)},$$

while

$$\int_{0}^{T} \varphi'(t)v(t) dt \in L^{2}(\Omega) \subset V^{*} + L^{2}(\Omega) \quad \text{and} \quad \int_{0}^{T} \varphi(t)w(t) dt \in V^{*} + L^{2}(\Omega).$$

Consequently, for all $\bar{u} \in V \cap L^2(\Omega)$,

$$0 \leq (w, v) - \left(\int_{0}^{T} \varphi'(t) v(t) dt + \int_{0}^{T} \varphi(t) w(t) dt, \bar{u}\right)_{V \cap L^{2}(\Omega)}$$

implying that

$$\int_0^T \varphi'(t)v(t) dt = -\int_0^T \varphi(t)w(t) dt$$

for all $\varphi \in C_0^{\infty}(0, T)$, i.e. w = v' = Lv. The fact that v(0) = 0 implying $v \in D(L)$ follows from (5) and (11) by standard argument (see e.g. [8] p. 176).

Now we are in a position to employ Proposition 1 to establish the existence of an element v in D(L) such that

$$\left(\frac{\partial v}{\partial t}, w\right)_{\mathscr{W}} + \widetilde{a}(v, w) + k(v, w)_{L^2(\mathcal{Q})} = (\widetilde{f}, w)_{\mathscr{W}}$$

for all $w \in \mathcal{W}$, for any given $\tilde{f} \in \mathcal{W}^*$. Reversing the substitution we get (cf. [6])

$$\left(\frac{\partial u}{\partial t}, e^{-kt} w\right)_{\mathcal{W}} + a(u, e^{-kt} w) = (f, e^{-kt} w)_{\mathcal{W}}$$

for all $w \in \mathcal{W}$, which implies that (10) holds. Since also $u \in D(L)$, the proof is complete.

Remark. It is clear from the proof of Theorem 1 that the Dirichlet null boundary condition in (4) can be replaced by any boundary condition associated to Vwith $W_0^{m,p}(\Omega) \subset V \subset W^{m,p}(\Omega)$. On the other hand, it can be shown that (3) admits also a periodic solution u(0)=u(T) if one chooses

$$D(L) = \{ u \in \mathcal{W} : u' \in \mathcal{W}^*, u(0) = u(T) \}.$$

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