

CONCIRCULAR TRANSFORMATIONS OF RIEMANNIAN MANIFOLDS

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Introduction. In this paper we deal with connected Riemannian manifolds (M, g) , (\bar{M}, \bar{g}) of dimension n and of class C^3 at least. We shall denote their sectional curvature tensors by R, \bar{R} , their Ricci tensors by r, \bar{r} , and their scalar curvatures by S, \bar{S} . The space of C^2 -vector fields on M will be denoted by $\Gamma(M)$.

With every strictly positive scalar function u of class C^2 on M , we associate the conformal deformation $g \mapsto u^{-2}g$ of (M, g) . The curvature tensors of $(M, \bar{g} = u^{-2}g)$ are then given, in local coordinates, by:

$$(0.1) \quad \bar{r}_{ij} - r_{ij} = \frac{n-2}{u} u_{i,j} + \left(\frac{\Delta u}{u} - (n-1) \frac{\text{grad}^2 u}{u^2} \right) g_{ij},$$

$$(0.2) \quad u^2 \bar{R}_{ijkl} - R_{ijkl} = -\frac{\text{grad}^2 u}{u^2} (g_{ik} g_{jl} - g_{il} g_{jk}) \\ + \frac{1}{u} (g_{ik} u_{j,l} + g_{jl} u_{i,k} - g_{il} u_{j,k} - g_{jk} u_{i,l}),$$

$$(0.3) \quad u^{-2} \bar{S} - S = 2(n-1) \left(\frac{\Delta u}{u} - \frac{n}{2} \frac{\text{grad}^2 u}{u^2} \right),$$

where the $u_{i,j}$ are the covariant derivatives of second order of u , and $\Delta u = g^{ij} u_{i,j}$. (These formulae follow from the usual ones by setting $u = e^{-\sigma}$.)

Definition. The scalar function u and the associated conformal deformation $g \mapsto u^{-2}g$ are said to be *concircular* if there exists a scalar function ϱ such that

$$(0.4) \quad u_{i,j} = \varrho g_{ij} \quad (i, j = 1, 2 \dots n).$$

Then, by setting $\tau = \varrho/u - (1/(2u^2)) \text{grad}^2 u$, the formulae (0.1), (0.2), (0.3) reduce to:

$$(0.5) \quad \bar{r}_{ij} - r_{ij} = 2(n-1)\tau g_{ij},$$

$$(0.6) \quad u^2 \bar{R}_{ijkl} - R_{ijkl} = 2\tau (g_{ik} g_{jl} - g_{il} g_{jk}),$$

$$(0.7) \quad u^{-2} \bar{S} - S = 2n(n-1)\tau.$$

More generally, if (M, g) and (\bar{M}, \bar{g}) are two Riemannian manifolds of the same dimension n , a morphism $f: M \rightarrow \bar{M}$ is said to be *concircular* if it is conformal and if there exists a scalar function ϱ on M such that $u = |f'|^{-1}$ satisfy (0.4). In other

words $f: (M, g) \rightarrow (\bar{M}, \bar{g})$ is concircular if, and only if, $g \mapsto f^* \bar{g}$ is a concircular deformation of (M, g) .

A conformal morphism f such that $|f'|$ is constant will be called a *similarity*; a conformal deformation $g \mapsto u^{-2}g$ such that u is constant will be said to be a *homothety*.

Concircular transformations have been introduced by K. Yano [13] as conformal transformations preserving geodesic circles (curves whose normal parametrizations satisfy $d^3x/ds^3 = k(dx/ds)$ with $k = \text{const.}$). Later, W. O. Vogel [12] proved that every morphism preserving geodesic circles is necessarily conformal; and Y. Tashiro [9] gave a classification of complete Riemannian manifolds admitting a concircular field u (i.e. satisfying (0.4) but not necessarily >0).

Let us notice that the characterization of the sphere given by M. Obata [8] sets upon this classification. For other papers relative to concircular transformations, see [5, 8, 10]. An equation close to (0.4) has been studied by J. Lafontaine [7].

In this paper, we first review the main results concerning concircular deformations (Section 1); then we shall set some apparently new results, and examine the special case $\tau=0$ (Sections 2, 3, 4). Most part of these results are extensible to pseudo-Riemannian manifolds.

1. Preliminaries. At first let us notice that, if $n \geq 3$, either relation (0.5), (0.6) involves (0.4) with $\varrho = \tau u + (1/(2u)) \text{grad}^2 u$. It easily follows:

Property 1.1. *Any conformal mapping between Einstein manifolds of dimension $n \geq 3$ is concircular.*

Conversely if $f: (M, g) \rightarrow (\bar{M}, \bar{g})$ is concircular, and if (M, g) is an Einstein space [resp. a space with constant sectional curvature], then so is (\bar{M}, \bar{g}) .

Property 1.2. *If $u: M \rightarrow \mathbf{R}$ is concircular (satisfying (0.4)) then:*

- a) *For any constant λ , $u + \lambda$ is concircular; and u^{-1} is concircular on $(M, u^{-2}g)$.*
- b) *There exists locally a function G such that*

$$(1.1) \quad \text{grad}^2 u = G(u) \quad \text{and} \quad \varrho = \frac{1}{2} G'(u).$$

- c) *For any vector fields X, Y on M*

$$(1.2) \quad R(X, Y). \text{grad} u = (L_X \varrho)Y - (L_Y \varrho)X.$$

Proof. The first assertion a) is obvious; for $n \geq 3$ the second one can be obtained by exchanging g and \bar{g} .

To prove b), we notice that, with intrinsic notations, (0.4) is equivalent with

$$(1.3) \quad \forall X \in \Gamma(M): \quad \nabla_X \text{grad} u = \varrho X$$

which implies

$$\nabla_X \text{grad}^2 u = 2\varrho X. \text{grad} u = 2\varrho \nabla_X u$$

or, in other terms, $d(\text{grad}^2 u) = 2\varrho du$.

Finally (1.2) follows from (1.3) by covariant differentiation.

Property 1.3. *In order that $u: M \rightarrow \mathbf{R}$ be concircular, it is necessary and sufficient that there exist local coordinates (x_i) , with $x_1 = u$, such that the metric of M be*

$$(1.4) \quad ds^2 = \frac{du^2}{G(u)} + G(u) \sum_{i,j \geq 2} \gamma_{ij}(x_2, \dots, x_n) dx_i dx_j$$

with $\varrho = (1/2)G'(u)$, or equivalently:

$$(1.5) \quad ds^2 = dv^2 + \varphi^2(v) \sum_{i,j \geq 2} \gamma_{ij}(x_2, \dots, x_n) dx_i dx_j$$

with $v = \int [G(u)]^{-1/2} du$ and $\varphi^2(v) = G(u)$.

Obviously, the function $G(u) = \text{grad}^2 u$ need not be defined at stationary points of u ; but on a complete manifold, there are at most two such points (cf. [10]).

For the applications of concircular properties to Einstein or other special spaces, see [2], [5], [9], [10], [11], [12], [13].

2. Conformal properties. From the results reviewed in Section 1, we easily infer

Lemma 2.1. *If $u: M \rightarrow \mathbf{R}$ is concircular (i.e. satisfies (0.4)), then*

a) *the u -hypersurfaces (defined by $u = \text{Const.}$) are totally umbilical, of constant normal curvature $\varrho/|\text{grad } u|$.*

b) *the integral curves of $\text{grad } u$ are geodesics whose tangent at any point is an eigen direction of the Ricci tensor.*

The proof is classical; the last assertion follows from (1.2). In [4] we proved that the ‘‘conformal circles’’ of E. Cartan and K. Yano are the curves which, by a suitable conformal deformation of M can be changed into geodesics whose tangent is an eigen direction of the Ricci tensor. By looking for a converse of Lemma 2.1, we obtain:

Theorem 2.2. *Let (M, g) be a Riemannian manifold and $u: M \rightarrow \mathbf{R}$ a strictly positive scalar function having only isolated stationary points. In order that there exists a metric \tilde{g} , conformal to g , such that u be concircular on (M, \tilde{g}) , it is necessary and sufficient that*

- i) *the u -hypersurfaces be totally umbilical,*
- ii) *their orthogonal trajectories be conformal circles.*

Proof. The necessity of these conditions follows from Lemma 2.1, since they are invariant under a conformal deformation.

Conversely we know (cf. [3]) that the condition i) implies the existence of local coordinates x_i , with $x_1 = u$, such that the metric of M is

$$ds^2 = A^2 du^2 + B^2 \sum_{i,j \geq 2} \gamma_{ij}(x_2, \dots, x_n) dx_i dx_j.$$

If the condition ii) is satisfied, the curves $x_i = \text{Const.}$ ($i \geq 2$) are still conformal

circles for the metric ds^2/A^2 ; and since they are geodesics for this new metric, $\partial/\partial u$ must be an eigen vector for the Ricci tensor. Now the $(1, j)$ -components ($j \neq 1$) of the Ricci tensor for ds^2/A^2 are given by

$$R_{1j} = -(n-2) \frac{\partial^2}{\partial u \partial x_j} \text{Log} \left(\frac{B}{A} \right)$$

and therefore the condition ii) is equivalent with the existence of two positive functions α, β such that

$$\frac{B}{A} = \alpha(u) \beta(x_2, \dots, x_n).$$

By setting $\bar{\gamma}_{ij} = \beta \gamma_{ij}$, we have

$$\frac{ds^2}{A^2} = du^2 + \alpha^2(u) \sum_{i, j \geq 2} \bar{\gamma}_{ij}(x_2, \dots, x_n) dx_i dx_j$$

and the Property (1.3) shows that u is concircular for the metric $ds^2/(\alpha A^2)$.

Let us notice also that $\int \alpha du$ is concircular for ds^2/A^2 . On the other hand we have:

Lemma 2.3. *If u is concircular on (M, g) , and if θ is a differentiable function on $u(M)$, the only metrics conformally equivalent with g which admit $\theta(u)$ as a concircular field are given by $\bar{g} = C|\theta'|g$, with $C = \text{Const}$.*

Application: Conformally flat manifolds admitting a concircular deformation. Starting with \mathbf{R}^n we have to look for functions $u > 0$ such that the u -hypersurfaces be totally umbilical and their orthogonal trajectories be conformal circles: in other words, u -hypersurfaces are hyperspheres (or hyperplanes) whose orthogonal trajectories are circles (or straight lines); and they must belong to a bundle of spheres or hyperplanes. By using a Möbius transformation, we are brought back to the three typical bundles, respectively defined by

$$\text{i) } \Sigma x_i^2 = \text{Const.}, \quad \text{ii) } x_1 = \text{Const.}, \quad \text{iii) } \frac{x_2}{x_1} = \text{Const.}$$

Therefore, if u is concircular on a conformally flat manifold (M, g) there exist local coordinates x_i and a function θ of one variable such that

$$u = \theta(\Sigma x_i^2), \quad u = \theta(x_1) \quad \text{or} \quad u = \theta(x_2/x_1)$$

and, for a suitable choice of the function $\sigma(x_1, \dots, x_n)$:

$$ds^2 = e^{2\sigma} \Sigma dx_i^2.$$

Now it can be directly checked that Σdx_i^2 admits x_1 and Σx_i^2 for concircular

fields, while $(x_1^2+x_2^2)^{-1}\Sigma dx_i^2$ admits $\text{arc tg}(x_2/x_1)$ as a concircular field. With help of Lemma 2.3, we can state:

Theorem 2.4. *The conformally flat metrics admitting a concircular field are locally given, by suitable choice of coordinates, by*

$$ds^2 = \varphi(\Sigma x_i^2)\Sigma dx_i^2, \quad ds^2 = \varphi(x_1)\Sigma dx_i^2$$

or

$$ds^2 = (x_1^2+x_2^2)^{-1}\varphi(\text{arc tg } x_2/x_1)\Sigma dx_i^2$$

where φ is an arbitrary function of one variable; and the associated concircular fields are the primitives of φ .

This result completes Theorem 2 of [6]. Let us notice that, by setting $u = \text{arc tg}(x_2/x_1)$ and $v = (1/2)\text{Log}(x_1^2+x_2^2)$, the metrics of the third type can also be written

$$ds^2 = \varphi(u)(du^2 + dv^2 + e^{-2v}\sum_{i \geq 3} dx_i^2).$$

The global existence of concircular fields depends on the topology of the manifold.

3. A special case: quasi-similarities. **Definition 3.1.** *A conformal deformation [resp. a conformal morphism f] will be called quasi-homothetic [resp. a quasi-similarity] if there exists a scalar function ϱ such that the associated function u [resp. the function $u = |f'|^{-1}$] satisfies*

$$(3.1) \quad u_{i,j} = \varrho g_{ij} \quad \text{and} \quad \text{grad}^2 u = 2\varrho u.$$

(In other terms: u is concircular and the associated function $\tau = \varrho/u - (1/(2u^2))\text{grad}^2 u$ is null.)

If $n \geq 3$, the conditions 3.1 express that the Ricci and sectional curvatures of M are transformed in the same way as under an homothety [resp. a similarity] of ratio u^{-1} (see formulae (0.5) and (0.6)). In particular, any conformal morphism of Ricci-flat manifolds (i.e. with Ricci curvature zero) of dimension $n \geq 3$ is automatically a quasi-similarity. More precisely, we have:

Lemma 3.1. *Let (M, g) be a flat [resp. Ricci-flat] manifold of dimension $n \geq 3$, and $f: (M, g) \rightarrow (\bar{M}, \bar{g})$ a conformal morphism. In order that $(f(M), \bar{g})$ be flat [resp. Ricci-flat] it is necessary and sufficient that f be a quasi-similarity.*

Quasi-similarities have been studied by us in [5]. Let us recall some results.

Lemma 3.2. *If $u = M \rightarrow \mathbf{R}$ satisfies (3.1), then ϱ is a constant; and for any vector fields X, Y on M , we have*

$$(3.2) \quad R(X, Y) \text{ grad } u = 0,$$

Lemma 3.3. *In order that $u: M \rightarrow \mathbf{R}$ be quasi-homothetic, it is necessary and sufficient that there exists a constant ϱ and local coordinates (x_i) , with $x_1 = u$, such that:*

$$(3.3) \quad ds^2 = \frac{du^2}{2\varrho u} + u \sum_{i,j \geq 2} \gamma_{ij}(x_2, \dots, x_n) dx_i dx_j.$$

(This is a special case of Property 1.3.)

For brevity, we shall say that a quasi-homothety [resp. a quasi-similarity] is proper if the associated function u is not constant.

Theorem 3.4. *A complete Riemannian manifold does not admit any proper quasi-homothety or quasi-similarity.*

Proof. On any geodesic γ satisfying $dx/ds = \text{grad } u / |\text{grad } u|$, we have $du/ds = (2\varrho u)^{1/2}$ and $d^2u/ds^2 = \varrho$; hence, if $\varrho \neq 0$: $2u = \varrho(s - s_0)^2$; and if s could run from $-\infty$ to $+\infty$, u would take the value zero.

The case of \mathbf{R}^n and of conformally flat manifolds. First of all, on \mathbf{R}^n , the only nonconstant solutions of (3.1) are the functions

$$(3.4) \quad u = \frac{1}{2} \varrho \sum (x_i - a_i)^2 \quad (\varrho, a_i = \text{Const.})$$

This easy remark provides a very short proof of the theorem of Liouville in class C^3 : namely, if U is an open set of \mathbf{R}^n ($n \geq 3$) and if $f: U \rightarrow \mathbf{R}^n$ is a conformal (not necessarily injective) morphism, then, from Lemma 3.1, f is a quasi-similarity and $u = |f'|^{-1}$ satisfies (3.4) for some values of ϱ, a_1, \dots, a_n . If $\varrho = 0$, $u = \text{Const.}$ and f is a similarity. If $\varrho \neq 0$, let be j the inversion $x \mapsto a + (2/\varrho)|x - a|^{-2}(x - a)$. Then we have $|f'(x)| = |j'(x)| = |j'(j(x))|^{-1}$, hence $|(f \circ j)'(x)| = 1$ and $f \circ j$ is an isometry. In both cases f is a Möbius transformation.

On another side, we may complete Lemma 2.3 and Theorem 2.4 by stating

Lemma 3.5. *If u is quasi-homothetic for (M, g) , the only metrics, conformally equivalent with g , which admit a nonconstant function $\theta(u)$ as quasi-homothetic, are of the type $\tilde{g} = Cu^{\lambda-1}g$ with $C, \lambda = \text{Const.}$, $\lambda \neq 0$, the function θ then being $\theta(u) = ku^\lambda$ ($k = \text{Const.}$).*

Theorem 3.6. *The conformally flat metrics admitting a quasi-homothetic deformation are locally given, with suitable coordinates, by:*

$$ds^2 = [\Sigma(x_i^2)]^{\lambda-1} \Sigma dx_i^2, \quad ds^2 = e^{\lambda x_1} \Sigma dx_i^2 \quad \text{or} \\ ds^2 = e^{\lambda u} (du^2 + dv^2 + e^{-2v} \sum_{i \geq 3} dx_i^2)$$

where $\lambda \neq 0$ is a constant.

Among these metrics there is no one of constant curvature $\neq 0$, as we could infer from (3.2).

4. Concircular deformations of submanifolds. The restriction to a submanifold of a concircular transformation is still conformal, but not necessarily concircular. In fact we have:

Theorem 4.1. Let $u: M \rightarrow \mathbf{R}$ concircular. In order that the restriction of u to a submanifold V be concircular it is necessary and sufficient that at any point of V either $\text{grad } u$ be tangent to V or the normal component N of $\text{grad } u$ be an umbilical direction for V .

Proof. We know that $v = u|_V$ is concircular if, and only if, there exists a function σ on V such that

$$(4.1) \quad \forall X \in \Gamma(V): \bar{\nabla}_X(\text{grad } v) = \sigma X,$$

where $\bar{\nabla}_X$ is the induced connection on V . Now $\text{grad } v = T = \text{grad } u - N$ is the tangential component of $\text{grad } u$, and $\bar{\nabla}_X T$ is the tangential component of $\nabla_X T$. By using (1.3) we see that the condition (4.1) is realized if, and only if, $\nabla_X N - (\rho - \sigma)X$ is normal to V ; and, if $N \neq 0$, this means that N is an umbilical direction for V .

This last condition is realized, in particular, if $\text{grad } u$ is normal to V at any point; in that case v is constant and $\sigma = 0$.

If u is quasi-homothetic (which implies $\text{grad}^2 u = 2\rho u$ and $\rho = \text{Const.}$) and if we want $v = u|_V$ to be quasi-homothetic, we have to set the additional condition $\text{grad}^2 v = 2\sigma v$ with $\sigma = \text{Const.}$ This is realized if and only if $|T|^2/|N|^2 = \sigma/(e - \sigma) = \text{Const.}$, i.e. if the angle of $\text{grad } u$ with V is constant. We can state:

Theorem 4.2. Let $f: M \rightarrow \bar{M}$ be a quasi-similarity and V a submanifold of M . In order that the restriction of f to V be a quasi-similarity, it is necessary and sufficient that the field $\text{grad}(|f'|^{-1})$ be tangent to V , or that it make a constant angle with V and its normal component be an umbilical direction for V .

A special case: Hypersurfaces of an Einstein manifold. If V is an hypersurface satisfying the second condition stated in Theorem 4.1, then V is totally umbilical with scalar normal curvature $\lambda = (\sigma - \rho)/|N|$. Now it is elementary to check that, in an Einstein space, the scalar normal curvature of a totally umbilical hypersurface is constant. In that case, the angular condition of Theorem 4.2 implies $|T| = \text{Const.}$ (since $(\sigma - \rho)/|N| = \text{Const.}$), hence $\text{grad}^2 v = 2\sigma v = \text{Const.}$, and $v = \text{Const.}$, which is realized if, and only if, $N = 0$. We can state:

Theorem 4.3. Let M be an Einstein space, and $u: M \rightarrow \mathbf{R}$ a quasi-homothetic deformation. In order that the restriction of u to an hypersurface V be quasi-homothetic, it is necessary and sufficient that V be tangent or normal to the vector field $\text{grad } u$.

By using a previous remark, we have:

Theorem 4.4. *Let (M, g) , (\bar{M}, \bar{g}) , be two Ricci-flat Riemannian manifolds of dimension $n \geq 4$, $f: M \rightarrow \bar{M}$ a conformal morphism, and V a flat [resp. Ricci-flat] hypersurface of M . In order that $f(V)$ be flat [resp. Ricci-flat] it is necessary and sufficient that the field $\text{grad}(|f'|^{-1})$ be tangent or normal to V .*

In particular, the only flat hypersurfaces of \mathbf{R}^n whose image, under an inversion with pole 0, is a flat hypersurface, are parts of cones with vertex 0 (this result being also true for $n=3$).

However these results cannot be extended to submanifolds of co-dimension ≥ 2 , as is proved by the following counter-example which infirms an assertion of [1].

Example. Let V be the submanifold of \mathbf{R}^{2p} , image of the domain $(t_i > 0)$ of \mathbf{R}^p under the imbedding f of components

$$f_k(t_1, \dots, t_p) = \frac{1}{\sqrt{2}} t_k \cos(\text{Log } t_k) \quad f_{k+p} = \frac{1}{\sqrt{2}} t_k \sin(\text{Log } t_k) \quad (1 \leq k \leq p).$$

We have $\sum_{i=1}^{2p} df_i^2 = \sum_{k=1}^p dt_k^2$, which proves that V is flat.

The image of V under the inversion $j: x \mapsto |x|^{-2}x$ admits the parametrization $g = j \circ f$, which satisfies

$$\sum_{i=1}^{2p} dg_i^2 = \sum_{i=1}^{2p} \frac{df_i^2}{|f|^4} = \frac{4}{|t|^4} \sum_{k=1}^p dt_k^2.$$

So $j(V)$ is flat, although V is neither tangent nor orthogonal to the field $\text{grad } |j'|^{-1}$. In fact the tangential and normal components of $\text{grad } |j'(x)|^{-1} = 2x$ at the point $x = f(t)$ are given by:

$$N_k = f_k + f_{k+p}, \quad N_{k+p} = f_{k+p} - f_k \quad (1 \leq k \leq p)$$

$$T_k = f_k - f_{k+p}, \quad T_{k+p} = f_k + f_{k+p} \quad (1 \leq k \leq p).$$

We can check that N is an umbilical direction for V , and that $\text{grad } |j'|^{-1}$ makes an angle of $\pi/4$ with V . Thus conditions of Theorem 4.2 are exactly fulfilled.

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