

QUASICONFORMAL MAPPINGS WITHOUT BOUNDARY EXTENSIONS

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1. According to the classical theorem of C. Carathéodory [1] and of W. F. Osgood and E. H. Taylor [6], a conformal mapping $f: D \rightarrow D'$ between two Jordan domains D and D' in the complex plane C always has a *boundary extension*, i.e. there is a homeomorphism $f^*: \bar{D} \rightarrow \bar{D}'$ of the respective closed domains such that $f^*|_D = f$. As it is well known, the theorem holds for planar quasiconformal mappings as well. In fact, G. Faber's proof for conformal mappings carries over to the quasiconformal case with minor modifications only ([3], cf. also R. Courant [2]; Lehto-Virtanen [5], pp. 44—46). J. Väisälä proved in [7] the existence of a boundary extension for all quasiconformal mappings $f: D \rightarrow D'$ between n -dimensional Jordan domains $D, D' \subset R^n$ quasiconformally equivalent to the unit ball $B^n \subset R^n$, $n \geq 2$ (also in Väisälä [8], pp. 51—67). But unlike the planar case, even a Jordan domain $D \subset R^n$ homeomorphic to the unit ball B^n is not necessarily quasiconformally equivalent to B^n when $n \geq 3$ (Gehring-Väisälä [4]). We shall give below an example which shows that for arbitrary Jordan domains $D, D' \subset R^n$, $n \geq 3$, a quasiconformal mapping $f: D \rightarrow D'$ does not always have a boundary extension.

I wish to express here my gratitude to Vesa Lappalainen, who has made all the excellent drawings below using the computer facilities of the University of Jyväskylä. Furthermore, I would like to thank the Royal Swedish Academy of Sciences for supporting my stay at the Mittag-Leffler Institute during the academic year 1983—1984.

2. Let Γ be the spiral curve in the closed unit disc $\bar{B}^2 \subset C$ described by

$$\Gamma(r) = re^{(i\alpha/2)(r-r^{-1})}$$

for $0 \leq r \leq 1$, $\alpha > 0$ a constant. If $\varrho = \varrho(z) = \varrho(z, 0)$ is the *hyperbolic distance* of $z \in \bar{B}^2$ from the origin with respect to the *hyperbolic length element*

$$d\varrho = 2(1 - |z|^2)^{-1} |dz|,$$

and $\theta = \arg(z)$ the *argument* of z , the trace of Γ can also be given as

$$\Gamma = \left\{ z \in \bar{B}^2: \theta = -\frac{\alpha}{\sinh(\varrho)}, \quad 0 \leq \varrho \leq +\infty \right\}.$$

The curve Γ has *hyperbolic curvature*

$$\chi(\varrho) = \frac{1 + \alpha^{-2} \tanh^4(\varrho)}{\tanh(\varrho)[1 + \alpha^{-2} \tanh^2(\varrho)]^{3/2}}$$

at the parameter value $r = \tanh(\varrho/2)$. Now the boundary of the domain

$$G = \left\{ z \in \mathbf{C}: 0 < |z| < 1, \left| \theta + \frac{\alpha}{\sinh(\varrho)} \right| < \frac{\pi}{2} \right\}$$

consists of a circular arc together with two spirals $\Gamma_{\pm} = \pm i\Gamma$ (cf. Figure 1; here as well as in all subsequent drawings $\alpha=2$). Because the closed domain \bar{G} lies to the right of the boundary arc Γ_+ , and the hyperbolic curvature of Γ_+ is positive, we can define in \bar{G} a *hyperbolic orthogonal projection* $p: \bar{G} \rightarrow \Gamma_+$ such that for all $z \in \bar{G}$ the hyperbolic arc $zp(z) \subset \bar{G}$ is perpendicular to Γ_+ and that $\varrho(z, p(z))$ is the hyperbolic distance of z from Γ_+ ,

$$\varrho(z, p(z)) = \varrho(z, \Gamma_+) = \min_{z' \in \Gamma_+} \varrho(z, z').$$

The projection p is easily seen to be infinitely differentiable in G . Furthermore, the positive curvature of Γ_+ implies that p is *locally strictly contractive* in G ,

$$\varrho(p(z), p(z_0)) < \varrho(z, z_0)$$

for all $z \neq z_0$ in a sufficiently small neighbourhood of $z_0 \in G$.

If $T(\varrho)$ is a primitive of

$$(1 + \alpha^2 \tanh^{-2}(\varrho))^{1/2},$$

we can define by $\tau(z) = T(\varrho(z))$, $z \in \Gamma_+$, a *hyperbolic length scale* on Γ_+ such that

$$\varrho_+(z_1, z_2) = |\tau(z_1) - \tau(z_2)|$$

gives the hyperbolic length of the subarc of Γ_+ with endpoints $z_1, z_2 \in \Gamma_+$. As $\tau(0) = -\infty$, $\tau(i) = +\infty$, the spiral Γ_+ is infinitely long in both directions. We extend τ to a function $\tau: \bar{G} \rightarrow \bar{\mathbf{R}}$ by setting

$$\tau(z) = \tau(p(z))$$

for arbitrary $z \in \bar{G}$.

3. With respect to the (quasi) hyperbolic length element

$$d\sigma = \frac{ds}{r}, \quad r = (x_1^2 + x_2^2)^{1/2}$$

in $\bar{\mathbf{R}}^3 = \mathbf{R}^3 \cup \{\infty\}$ the x_3 -axis forms the circle at infinity, and a hyperbolic isometry identifying the closed unit disc $\bar{B}^2 \subset \mathbf{C}$ with the closed half-plane $\{x \in \bar{\mathbf{R}}^3: x_2 = 0, x_1 \geq 0\}$ can be defined by

$$x_1 + ix_3 = h(z) = \frac{1-z}{1+z}.$$

If we rotate the image $h(\bar{G})$ of \bar{G} around the x_3 -axis, we get a *closed Jordan domain*

(a sectorial cross cut in Figure 2)

$$\bar{D} = \left\{ x \in \mathbf{R}^3 : \left| \psi + \frac{\alpha}{\sinh(\sigma)} \right| \leq \frac{\pi}{2}, \quad 0 \leq \sigma \leq +\infty \right\},$$

where

$$\psi = \psi(x) = \arg \left(\frac{1-r-ix_3}{1+r+ix_3} \right),$$

and

$$\sigma = \sigma(x) = \sigma(x, S^1)$$

is the *hyperbolic distance* of $x \in \mathbf{R}^3$ from the unit circle S^1 of the plane $\mathbf{R}^2 = \{x \in \mathbf{R}^3 : x_3 = 0\}$. The boundary of \bar{D} consists of two topological discs

$$E_{\pm} = \left\{ x \in \mathbf{R}^3 : \psi + \frac{\alpha}{\sinh(\sigma)} = \pm \frac{\pi}{2}, \quad 0 \leq \sigma \leq +\infty \right\}$$

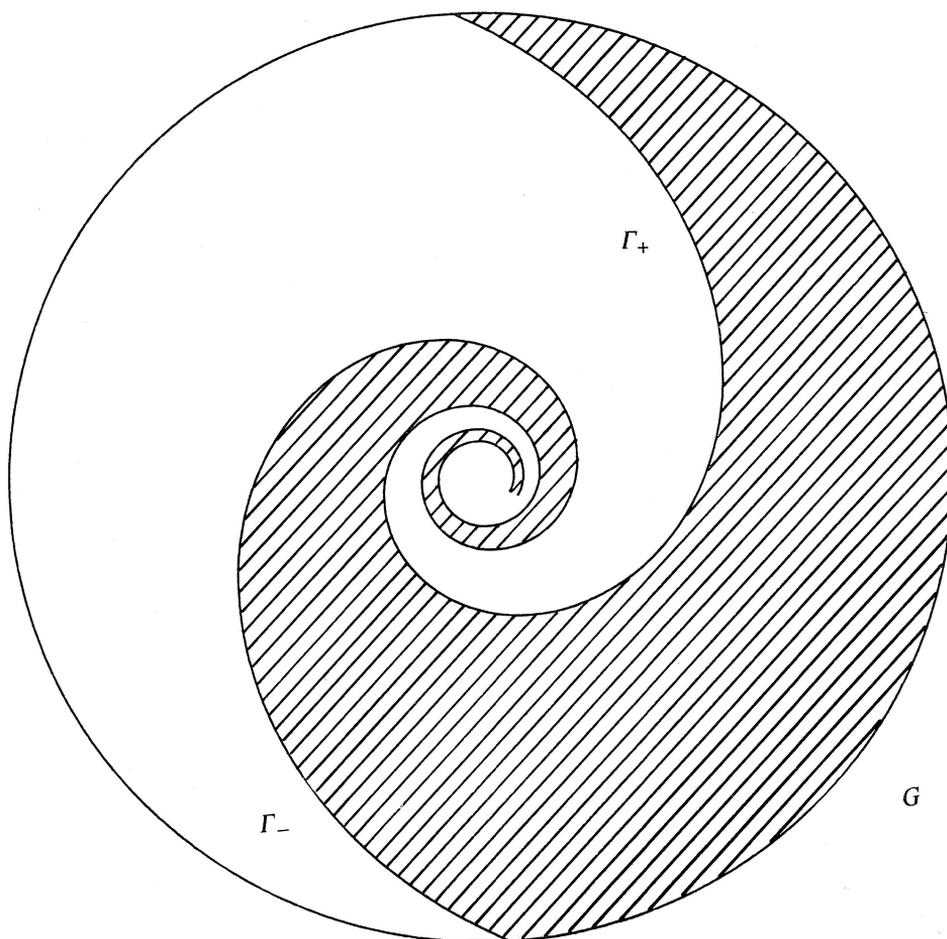


Figure 1

glued together along the circle $S^1 = E_+ \cap E_-$. The function τ extends by rotation to a *parameter function* $\tau: \bar{D} \rightarrow \bar{\mathbf{R}}$ such that $\tau^{-1}(-\infty) = S^1$ and $\tau^{-1}(+\infty) = \{(0, 0, -1)\}$. As in the preceding paragraph, we can define in the whole domain \bar{D} outside the x_3 -axis a *locally contractive hyperbolic orthogonal projection* p into the lower half-boundary E_+ such that $\tau(x) = \tau(p(x))$ for all x in \bar{D} outside the x_3 -axis.

If we let $S^1 \subset E_+$ collapse to a point and set

$$\varphi(x) = \arg(x_1 + ix_2)$$

for $x \in \mathbf{R}^3$, we see that

$$\theta(x) = e^{\tau(x) + i\varphi(x)}$$

defines an *isometry* and thus a *conformal mapping* of E_+ onto the Riemann sphere $\bar{\mathbf{C}}$ with respect to the *hyperbolic length element* $d\sigma$ in E_+ and the *logarithmic length element*

$$dv = |z|^{-1}|dz|$$

in $\bar{\mathbf{C}}$, so that $\theta(S^1) = 0$ and $\theta(0, 0, -1) = \infty$.

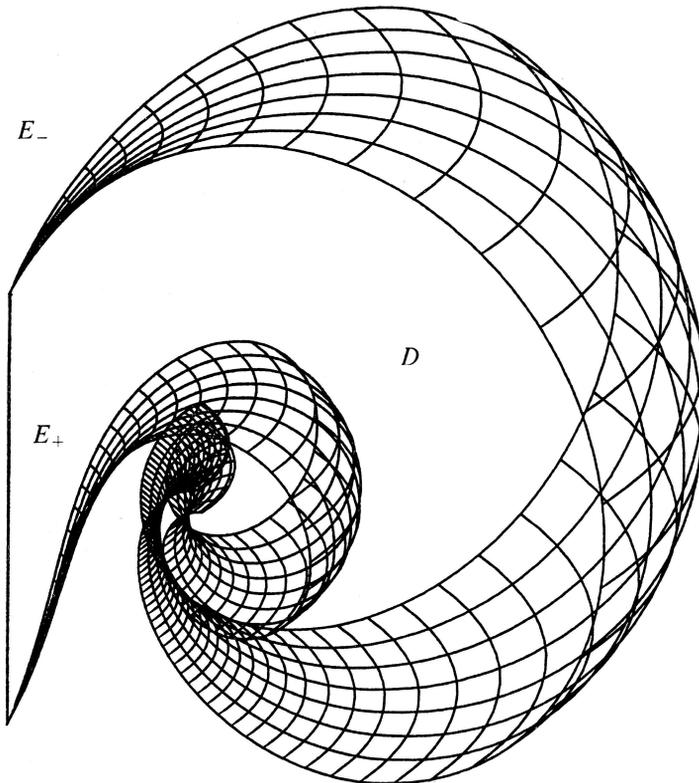


Figure 2

Using the complex notation

$$x = (\zeta, x_3) = (x_1 + ix_2, x_3) \in \mathbf{R}^3,$$

$$ax = (a\zeta, |a|x_3) \in \mathbf{R}^3$$

for $x \in \mathbf{R}^3$, $a \in \mathbf{C}$, we define for any real λ the mapping $f_\lambda: \bar{D} \setminus S^1 \rightarrow \bar{D} \setminus S^1$ by

$$f_\lambda(x) = \exp(i\lambda\tau(x))x.$$

The restriction $f_\lambda: E_+ \setminus S^1 \rightarrow E_+ \setminus S^1$ is quasiconformal for all $\lambda \in \mathbf{R}$, its symmetrized derivative having the eigenvalues

$$c_1(\lambda) = (1 + \lambda^2/2 + (\lambda^2 + \lambda^4/4)^{1/2})^{1/2},$$

$$c_2(\lambda) = c_1(\lambda)^{-1}$$

at all nonsingular points of E_+ . Now f_λ preserves the equidistance surfaces $S_t = \{x \in D: \sigma(x, E_+) = t\}$, $t > 0$, in D , and because the projection p is locally contractive, we see, using appropriate local coordinates, that the eigenvalues $c_1(x, \lambda) \cong c_2(x, \lambda) \cong c_3(x, \lambda) > 0$ of the symmetrized derivative of f_λ satisfy

$$c_1(x, \lambda) = c_3(x, \lambda)^{-1} \cong c_1(\lambda),$$

$$c_2(x, \lambda) = 1$$

at all points x of D outside the x_3 -axis. Thus $f_\lambda: D \rightarrow D$ is quasiconformal with dilatations

$$K(f_\lambda) = K_o(f_\lambda) = K_l(f_\lambda) = c_1(\lambda)^3.$$

Because $\tau(x) \rightarrow -\infty$ as $x \rightarrow S^1$, we have

$$C(f_\lambda, b) = S^1$$

for the cluster set at any boundary point $b \in S^1 \subset \partial D$ when $\lambda \neq 0$. Thus in this case the quasiconformal mapping $f_\lambda: D \rightarrow D$ does not have any boundary extension. To visualize the situation we have depicted in Figure 3 the image of $\Gamma' = h(\Gamma) \cap D$ when $\lambda = 0.25$.

We could also choose a function $\lambda(\tau)$ with a uniformly bounded derivative $\lambda'(\tau)$ converging to 0 when $\tau \rightarrow -\infty$ but such that $\lambda(\tau) \rightarrow -\infty$ at the same time, and define $f: D \rightarrow D$ by setting

$$f(x) = \exp[i(\lambda \circ \tau)(x)]x$$

for all $x \in D$. Then also $f: D \rightarrow D$ would be a quasiconformal mapping having $C(f, b) = S^1$ as cluster set at all $b \in S^1$ but with the local maximal dilatation $K(x, f)$ approaching one when x approaches S^1 .

4. Remarks. (i) The example above was chosen because it allows a fairly simple and explicit representation. The Jordan domain D has also quite nice symmetry properties, e.g. the Möbius transformation generated by the successive reflections in the plane \mathbf{R}^2 and in the unit sphere $S^2 \subset \mathbf{R}^3$ maps D conformally onto its exterior. The boundary $\partial D = E_+ \cup E_-$ is quasiconformally collared with the exception of the

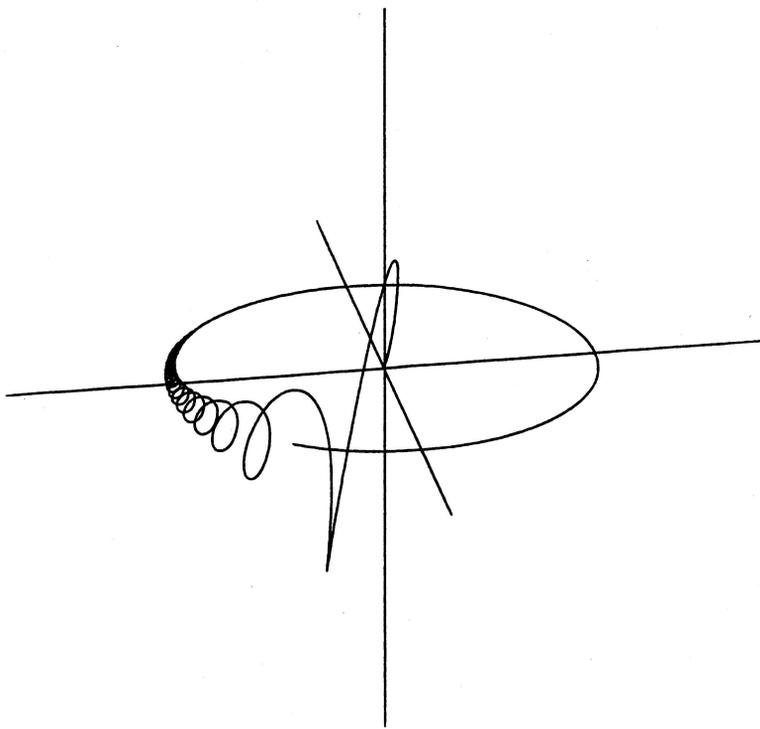


Figure 3

circle $S^1 = E_+ \cap E_-$. In fact, the mapping Ψ defined by

$$\Psi(x) = \left(\frac{e^{\tau(x)} \zeta}{|\zeta| \cosh \sigma(x, E_+)}, -e^{\tau(x)} \tanh \sigma(x, E_+) \right) \in \mathbb{R}^3$$

for $x = (\zeta, x_3) \in \bar{D}$ maps D homeomorphically onto a domain D^* in the lower half-space $x_3 < 0$ bounded by the plane $\bar{\mathbb{R}}^2 = \Psi(E_+)$ and by the quasiconformal sphere $E_-^* = \Psi(E_-)$, the singular part $S^1 = E_+ \cap E_-$ of the boundary collapsing onto the origin, $\Psi(S^1) = \{0\}$ (cf. Figure 4). The mapping Ψ preserves $\varphi(x) = \arg(\zeta)$, and $\sigma(\Psi(x), \mathbb{R}^2) = \sigma(x, E_+)$ for all $x \in D$. In the direction of the line $\varphi(x) = \varphi(x_0)$, $\sigma(x, E_+) = \sigma(x_0, E_+)$ the mapping Ψ has at $x_0 \in D$ the contraction coefficient

$$\kappa(x_0) = [1 + \chi(\sigma(p(x_0))) \tanh \sigma(x_0, E_+)]^{-1}.$$

Because we have $\sigma(x, E_-) \sim \alpha^{-1} \pi \sigma^2$ for the width of D and $\chi(\sigma) \sim \sigma^{-1}$ for the hyperbolic curvature when x approaches S^1 on E_+ , we see that κ is uniformly bounded away from 0 in D , so that also the mapping $\Psi: D \rightarrow D^*$ is quasiconformal. When $\alpha = 2$, $\kappa(x) > 1/3$ in the whole domain D , so that in this case $K(\Psi) < 9$.

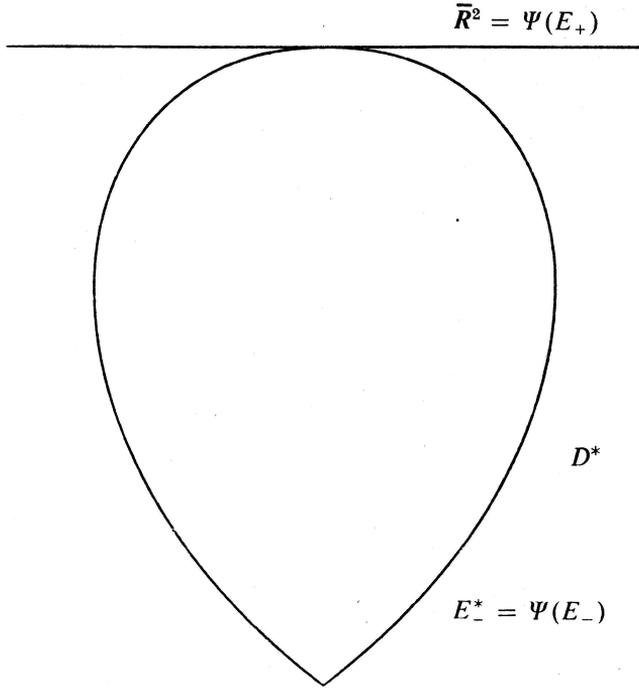


Figure 4

(ii) We can make the same construction in R^n , $n > 3$, using the (quasi)hyperbolic length element

$$d\sigma = (x_1^2 + \dots + x_{n-1}^2)^{-1/2} ds$$

and defining as above an n -dimensional Jordan domain

$$D_n = \left\{ x \in R^n : \left| \psi + \frac{\alpha}{\sinh(\sigma)} \right| < \frac{\pi}{2}, \quad 0 < \sigma \leq +\infty \right\}$$

such that the boundary of D_n contains the unit sphere S^{n-2} of the hyperplane $R^{n-1} = \{x \in R^n : x_n = 0\} \subset R^n$. Only the rotations require a somewhat more careful consideration than before. To this purpose we choose antisymmetric linear endomorphisms A_1, \dots, A_q of R^{n-1} such that the orbit of

$$O(t) = \prod_{j=1}^q \exp(tA_j) \in SO(n-1) \subset SO(n)$$

for $t \rightarrow \pm \infty$ is dense in the orthogonal group $SO(n-1)$ of R^{n-1} . Let $\tau: D_n \rightarrow R$ be the parameter function for D_n . For all real λ we can now define by

$$f_\lambda(x) = O(\lambda\tau(x))x$$

a quasiconformal mapping $f_\lambda: D_n \rightarrow D_n$ with

$$K(f_\lambda) \cong c_1(\lambda a)^n,$$

where

$$a = \sum_{j=1}^q \|A_j\|.$$

Furthermore, for all $b \in S^{n-2} \subset \partial D_n$

$$C(f_\lambda, b) = S^{n-2}$$

when only $\lambda \neq 0$.

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Received 16 December 1983