A NOTE ON A PROBABILISTIC DECOMPOSITION OF LINEAR DELTA MODULATOR OF A WIENER PROCESS

T. Koski

1. Introduction

Linear delta modulation (LDM) is a causal, recursive analog-to-digital (and vice versa) technique of data compression. The engineering work devoted to LDM and its modification is covered in [14]. Some of the research in the mathematical treatment of LDM is found in [5], [6], [13] and [17]. Further references e.g. to the works of T. Fine and J. Kiefer are found in [9].

This paper considers the LDM of a standard Wiener process (although some extensions are outlined). That this should be, in a certain sense, the proper way of tracking a time sampled Wiener process has been stated in [1]. Here we provide a probabilistic decomposition of the decoded process, by means of Ito's rule, viewing the decoded variable as a functional of the Wiener process. Other results on LDM of Wiener processes are found in [11].

The basic definitions of the LDM model are presented in Section 2. The main result, a probabilistic structure for the encoder, is given in Section 3. It turns out that the encoder can be written as a sum of a function of the predicted reconstruction error and a stochastic integral. This shows that there is a certain martingale structure associated with the decoded process, the properties of which are studied in this section. It is quite obvious that the representation can be extended to other (diffusion) sources. Explicit results are given for the Ornstein-Uhlenbeck case (see also [9]).

Section 4 contains an application of Malliavin's calculus on the predicted error part in the encoded process. It turns out that this part has a probability density with respect to the Lebesgue measure.

2. Linear delta modulation of a Wiener process

Let \((\Omega, \mathcal{F}, P)\) be a complete probability space and \(w^d = \{w_t\}_{t=0}^\infty\) be a real (source) stochastic process defined on it (in fact \(w^d\) is a time-sampled Brownian motion (B.M.)). Let \(d > 0\) and \(0 < c \leq 1\). The encoder of the LDM is defined by the predictor

\[
(2.1) \quad b_t = \text{sgn} (w_t - cz_{t-1})
\]
where we take

\begin{equation}
\text{sgn}(x) = \begin{cases} 
+1, & x > 0, \\
0, & x = 0, \\
-1, & x < 0.
\end{cases}
\end{equation}

In (2.1) the process \( z^d = \{z_{t_i}\}_{i=0}^\infty \) is the decoded sequence of random variables that approximate \( w^d \) and is recursively generated by means of the corrector

\begin{equation}
(2.2)
\end{equation}

\[ z_{t_i} = c z_{t_{i-1}} + d b_i. \]

The engineering terms for (2.3) are "ideal integration" in case \( c = 1 \) and "leaky integration" for \( c < 1 \). Further, \( d \) may be regarded as a quantization step. Solving (2.3) yields

\begin{equation}
(2.4)
\end{equation}

\[ z_{t_i} = c^i z_{t_0} + d \sum_{j=1}^{i} c^{i-j} b_j. \]

When dealing with LDM of B.M. it is natural to set \( z_{t_0} = 0 \). Then it follows for the leaky integrator that

\begin{equation}
(2.5)
\end{equation}

\[ |z_{t_i}| \leq \frac{d}{1 - c} \]

for every \( t_i \). Regard now the random variables \( w_{t_i} \) as samples at deterministic times of an underlying B.M. \( w = \{w_t \mid t \geq 0\} \) defined on \( (\Omega, \mathcal{F}, P) \). Let

\begin{equation}
(2.6)
\end{equation}

\[ \mathcal{F}_t = \sigma(w_s \mid 0 \leq s \leq t) \]

designate the sigma-algebra generated by the process \( w \) up to time \( t \). It is evident by construction that \( z_{t_i} \) cannot converge anywhere on \( \Omega \) as \( i \to \infty \), if \( w \) is the source process. Hence it follows that

2.1. **Proposition.** Let \( w^d \) be a sampled B.M. Then \( (z_{t_i}, \mathcal{F}_{t_i})_{i=0}^\infty \) cannot be an asymptotic martingale if \( 0 < c < 1 \).

The proof follows immediately by Proposition 2.2 in [4] in view of (2.5). In particular this means that \( (z_{t_i}, \mathcal{F}_{t_i})_{i=0}^\infty \) cannot be a martingale (sub- or quasi). It can be seen that a similar conclusion holds for the ideal integrator, too. However, we shall discover that a martingale structure is associated with LDM of B.M.

The basic point of departure is the following observation: (2.5) entails

\[ E|z_{t_i}|^2 \leq d^2/(1 - c)^2 \]

for leaky integration. Hence any \( z_{t_i} \) may be viewed as a square integrable functional of \( w \) up to \( t_i \). As is well established (c.f. [2] and [10], Theorem 5.6), any such functional of the Wiener process \( w^{t_i} = (w_t, \mathcal{F}_t)_{0 \leq t \leq t_i} \) can be written as a sum of an random variable and a stochastic integral.

Note also that \( E|z_{t_i}|^2 \leq c_i < \infty \) for some finite constant \( c_i \) if ideal integration is considered, since any \( z_{t_i} \) has a range consisting of some finite, countable number of values. Consequently we need not consider separately the two cases in Propositions 3.1 and 3.4.
3. The representation of LDM by means of a stochastic integral

First we make some elementary observations about the function

\begin{equation}
V(t, x; z, t_i) = \int_{-\infty}^{\infty} k(t, x - y; t_i) \text{sgn}(y - z) dy
\end{equation}

where \( z \in \mathbb{R} \) and

\begin{equation}
k(t, x; t_i) = \begin{cases} 
\frac{e^{-x^2/(4(t - t_i))}}{\sqrt{4\pi(t_i - t)}} & 0 \leq t < t_i \\
0 & t = t_i
\end{cases}
\end{equation}

is the heat kernel. The classical change of variable ([15], p. 32) \( y \rightarrow r \)

\begin{equation}
r = (y - x) \cdot (4(t_i - t))^{-1/2}
\end{equation}

gives after an elementary calculation that for \( \Theta = (z - x) / \sqrt{4\pi(t_i - t)} \)

\begin{equation}
V(t, x; z, t_i) = \text{erfc}(\Theta) - 1
\end{equation}

where \text{erfc} is the complementary error function

\begin{equation}
\text{erfc}(x) = \frac{2}{\sqrt{\pi}} \int_x^{\infty} e^{-r^2} dr
\end{equation}

([15], p. 10). By quick separate consideration of the three cases \( \text{sgn}(x - z) = \pm 1 \) or 0 one sees that

\begin{equation}
\lim_{t \downarrow t_i} V(t, x; z, t_i) = \text{sgn}(x - z)
\end{equation}

for every \( x \) and \( z \). (This is more than can be expected in the general case, c.f. [15], Chapter VII, and is the reason for the definition (2.2)). It is also a straightforward matter to check that the function \((t, x) \rightarrow V(t, x; z, t_i)\) solves (for fixed \( t_i \) and \( z \)) the backward heat equation

\begin{equation}
V'_t(t, x) + \frac{1}{2} V''_{xx}(t, x) = 0 \quad \text{for} \quad (t, x) \in [0, t_i] \times [-\infty, \infty]
\end{equation}

where \( V'_t \) and \( V''_{xx} \) denote partial differentiation. The boundary values are those in (3.6). The basic rules of stochastic calculus provide the link between (3.1)-(3.7) and the LDM for \( w^d \) (c.f. [3]).
3.1. Proposition. Let \( w^d \) consist of discrete time samples of a standard B.M. \( w \) and let \( z^d \) be the corresponding encoded process (evolving according to (2.3)). Then the equality

\[
 b_i = \text{sgn}(w_{t_i} - cz_{t_i-1}) = \text{erfc} \left( \frac{cz_{t_i-1} - w_{t_i-1}}{\sqrt{4\pi (t_i - t_{i-1})}} \right) - 1 \\
+ \int_{t_{i-1}}^{t_i} \frac{1}{\sqrt{t_i - s}} e^{-\frac{(cz_{t_i-1} - w_s)^2}{4\pi(t_i - s)}} dw_s
\]

(3.8)

holds, \( P \)-almost surely, for any \( i \).

Proof. In view of (3.7) a formal application of Ito’s differentiation rule yields

\[
 V(t_i, w_{t_i}; cz_{t_i-1}, t_i) - V(t_{i-1}, w_{t_{i-1}}; cz_{t_{i-1}}, t_i) = \\
= \int_{t_{i-1}}^{t_i} V'_x(s, w_s; cz_{t_{i-1}}, t_i) \, dw_s.
\]

(3.9)

It may be noted that \( V'_x(s, w_s; cz_{t_{i-1}}, t_i) \) is \( \mathcal{F}_s \)-measurable, as it should be, and

\[
\int_{t_{i-1}}^{t_i} E \left[ V'_x(s, w_s; cz_{t_{i-1}}, t_i) \right]^2 \, ds < \infty.
\]

(3.10)

In order to check (3.10) we observe that

\[
 V'_x(s, x; z, t_i) = \begin{cases} 
  e^{-\frac{(z-x)^2}{4\pi(t_i - s)}} \, \frac{1}{\sqrt{t_i - s}} & s < t_i, \\
  0 & s = t_i.
\end{cases}
\]

(3.11)

which is in its turn readily established e.g. by differentiating (3.1) and performing the change of variable (3.3) in the resulting integral.

Here

\[
 E \left[ V'_x(s, w_s; cz_{t_{i-1}}, t_i) \right]^2 = \frac{1}{t_i - s} E \left[ e^{-\frac{(cz_{t_{i-1}} - w_s)^2}{2\pi(t_i - s)}} \right]
= \frac{1}{t_i - s} E \left[ e^{-\frac{(cz_{t_{i-1}} - w_s)^2}{2\pi(t_i - s)}} \right | \mathcal{F}_{t_{i-1}}]\right].
\]

Given \( \mathcal{F}_{t_{i-1}} \) the random variable \( w_s \) has a normal distribution \( N(w_{t_{i-1}}; s) \) and \( z_{t_{i-1}} \) has assumed a fixed value in some finite and countable set. Under these circumstances it can be calculated, in a straightforward manner, that for a constant \( M \)

\[
 E \left[ \left( e^{-\frac{(cz_{t_{i-1}} - w_s)^2}{2\pi(t_i - s)}} \right) \right | \mathcal{F}_{t_{i-1}}] = M\sqrt{t_i - s} E \left[ e^{y_s(t_i)} \right]
\]

(3.12)
Decomposition of delta modulator of a Wiener process

where \( y_s(i) \) is a random variable which is easily seen to be almost surely uniformly bounded in \( s \in [t_{i-1}, t_i] \). Hence

\[
\int_{t_{i-1}}^{t_i} V_x(s, w_s; z_{t_{i-1}}, t_i) \, dw_s
\]

is a well defined stochastic integral in Itô's sense and (3.8) is valid. Let us now set

\[
(3.13) \quad x_i(w) = \int_{t_{i-1}}^{t_i} \left( t_i - s \right)^{-1/2} \exp\left( -\left( cz_{t_{i-1}} - w_s \right)^2 / 4\pi (t_i - s) \right) \, dw_s,
\]

\[
(3.14) \quad F_{t_i}(w) = \left[ \text{erfc}\left( \frac{cz_{t_{i-1}} - w_{t_{i-1}}}{\sqrt{4\pi (t_i - t_{i-1})}} \right) - 1 \right].
\]

Evoking Proposition 3.1 and these notations in (2.4) yields the decomposition

3.2. Corollary.

\[
(3.15) \quad z_{t_i} = dc_i \sum_{j=1}^{i} e^{-jF_{t_j}(w)} + dc_i \sum_{j=1}^{i} e^{-jx_j(w)}.
\]

The elementary properties of stochastic integrals as well as the fact that every \( F_{t_i}(w) \) is \( \mathcal{F}_{t_{i-1}} \)-measurable entail, by virtue of (3.15), that the conditional variance of \( z_{t_i} \) equals

\[
(3.16) \quad E \left[ \left( z_{t_i} - E [z_{t_i} \mid \mathcal{F}_{t_{i-1}}] \right)^2 \mid \mathcal{F}_{t_{i-1}} \right] = E \left[ x_i^2(w) \mid \mathcal{F}_{t_{i-1}} \right],
\]

which would seem to indicate that some interesting information about the process \( \{z_{t_i}\}_{i=0}^{\infty} \) could be obtained in terms of the properties of the martingale \( (S_i, \mathcal{F}_i)_{i=0}^{\infty} \) where

\[
(3.17) \quad S_i = \sum_{j=1}^{i} x_j(w), \quad S_0 = 0.
\]

For example we find the following using Theorem 2.15 in [7]:

3.3. Proposition. Let \( \{z_{t_i}\}_{i=0}^{\infty} \) be the decoded sequence of the leaky integration LDM of B.M. Suppose that \( \sum_{i=1}^{\infty} \sqrt{t_i - t_{i-1}} < \infty \). Then

\[
(3.18) \quad \sum_{i=1}^{\infty} E \left[ x_i^2(w) \mid \mathcal{F}_{t_{i-1}} \right] < \infty
\]
almost surely, and
\[
(3.19) \quad \sum_{i=1}^{n} e^{i-\frac{1}{2}} x_i(w) \to 0
\]
almost surely, as \( n \to \infty \).

The proof will be published elsewhere. This result is mostly of theoretical interest, since in practice \( t_i - t_{i-1} \) is almost constant.

Suppose now that the process being linearly delta modulated is an Ornstein-Uhlenbeck process (O.U.) (or Gauss-Markov process). Denoting the time samples by \( \{x_i\}_{i=0}^{\infty} \) and letting \( \{z_i\}_{i=0}^{\infty} \) denote the corresponding output of the decoder, we obtain by explicit calculation exactly similar to above (but somewhat more arduous) that

**3.4. Proposition.** Let the process \( x = \{x_t \mid t \geq 0\} \) have the stochastic differential
\[
(3.20) \quad dx_t = -\mu x_t \, dt + dw_t, \quad x_0 = 0
\]
where \( w \) is a standard B.M. and \( \mu > 0 \).

Then
\[
(3.21) \quad \text{sgn}(x_t - cz_{t-1}) = \text{erfc}\left(\frac{\sqrt{\mu}(cz_{t-1} - x_{t-1} e^{-\mu(t_{t-1})})}{(1 - e^{-2\mu(t_{t-1})})^{1/2}}\right) - 1
\]
\[
\text{sgn}(x_t - cz_{t-1}) = \frac{2\mu}{\sqrt{\pi}} \int_{t_{t-1}}^{t} \frac{e^{-\mu(t_s)}}{\sqrt{1 - e^{-2\mu(t_s)}}} \exp\left(-\mu\left(x_s e^{-\mu(t_s)} - cz_{t-1}\right)^2 \right) dw_s.
\]

We omit the detailed proof but point out that the partial differential equation corresponding to (3.6)-(3.7) is in this case
\[
(3.22) \quad V_t' + \frac{1}{2} V_x'' - \mu x V_x' = 0 \quad \text{for} \quad (t, x) \in ]0, t_i[ x - \infty, \infty[, \quad t_{t_i}
\]
\[
(3.23) \quad \lim_{t \to t_i} V(t, x; z, t_i) = \text{sgn}(x - z).
\]
The statement of the counterpart of Corollary 3.2 is obvious. Further analysis of the Ornstein-Uhlenbeck case using this representation in order to derive results like in [6] and [13] is in progress, see [9].

The formula (3.21) provides some further insight to the probabilistic mechanism in the coder of LDM. The argument \( cz_{t-1} - x_{t-1} e^{-\mu(t_{t-1})} \) in \( \text{erfc}(\cdot) \) is nothing else but the difference between the predicted value of \( x_{t_i} \) and the predicted value of \( z_{t_i} \) given the information \( F_{t_i-1} \). We shall hence call the functional \( \mathbf{F}_{t_i}(w) \) defined in (3.14) the predicted-error transform.
4. The absolute continuity of the distribution induced by the predicted-error transform

We shall now prove that the random variable $F_{t_i}(w)$ in (3.14) induces a probability distribution with a density w.r.t. the Lebesgue measure. Since $F_{t_i}(w)$ is another functional of the Wiener process $w^{t_{i-1}} = (w_t, \mathcal{F}_t)$, $0 \leq t \leq t_{i-1}$, this proof is appropriately done as an application of Malliavin’s calculus (in the form elaborated in [12] and [16]).

$F_{t_i}(w)$ is a square integrable $\mathbb{E}[F_{t_i}(w)]^2 < \infty$ functional of $w^{t_{i-1}}$. Let us suppose that $u = \{u_s \mid 0 \leq s \leq t_{i-1}\}$ is a random process on $(\Omega, \mathcal{F}, \mathbb{P})$ with Lebesgue measurable and square integrable sample paths. We shall in the sequel select $u$ so that any $u_s$ will additionally be adapted to $\mathcal{F}_s$, although the work of Zakai and Nualart [12] shows that this is not necessary.

It will first be proved that the directional derivative of $F_{t_i}(w)$ in the $\int u_s \, ds$ direction defined as

$$D_u F_{t_i}(w) = \frac{\partial}{\partial \varepsilon} F_{t_i}(w + \varepsilon \int u_s \, ds) \big|_{\varepsilon = 0}$$

will exist almost surely. Then, roughly stated, if we can exhibit a process $u$ such that the requirements above are satisfied and such that

$$D_u F_{t_i}(w) \neq 0 \quad \text{a.s.}$$

our claim about the existence of the density will be established.

We need first a simple observation about the effects of a particular perturbation on linear delta modulation. Let us set for $\varepsilon > 0$

$$w_\varepsilon = \left\{ w_t + \varepsilon \int_0^t u_h \, dh \mid t \geq 0 \right\}.$$  

4.1. Lemma. Let $z^\varepsilon_{t_i}$ and $z_{t_i}$ designate the decoded variables corresponding to the LDM of the processes $w_\varepsilon$ and $w$, respectively. Then there exists a positive number $\varepsilon_{t_i}$ such that $z^\varepsilon_{t_i}$ and $z_{t_i}$ designate the decoded variables corresponding to the LDM of the processes $w_\varepsilon$ and $w$, respectively. Then there exists a positive number $\varepsilon_{t_i}$ such that

$$z^\varepsilon_{t_i} = z_{t_i} \quad P - \text{a.s.}$$

for every $\varepsilon \leq \varepsilon_{t_i}$ (or a modification of the process $z$ such that (4.3) holds).

Proof. We shall proceed inductively using (2.3). Since

$$z^\varepsilon_0 = z_0 = w_0 = 0,$$
$$z^\varepsilon_{t_i} = \text{sgn}(w_{t_i} + \varepsilon \int_0^{t_i} u_s \, ds),$$
$$z_{t_i} = \text{sgn}(w_{t_i}),$$
The equality (4.3) holds obviously for \( \varepsilon \leq \varepsilon_{t_{i-1}} \) with some \( \varepsilon_{t_{i-1}} \), with the exception of the event \( w_{t_{i}} = 0 \), the probability of which is zero, since \( w_{t_{i}} \) is continuously distributed. (Hence we can modify the variable \( z_{t_{i}} \) so that it has a value different from zero for all \( \omega \in \Omega \).)

Assume now that \( \varepsilon_{t_{i-1}} \) has been established so that \( z_{t_{i-1}}^\varepsilon = z_{t_{i-1}} \) almost surely for \( \varepsilon \leq \varepsilon_{t_{i-1}} \).

Then for \( \varepsilon \leq \varepsilon_{t_{i-1}} \)

\[
z_{t_{i}}^\varepsilon - z_{t_{i}} = c \left( z_{t_{i-1}}^\varepsilon - z_{t_{i-1}} \right) + d \left[ \text{sgn} \left( w_{t_{i}}^\varepsilon - cz_{t_{i-1}}^\varepsilon \right) - \text{sgn} \left( w_{t_{i}} - cz_{t_{i-1}} \right) \right]
= d \left[ \text{sgn} \left( w_{t_{i}}^\varepsilon - cz_{t_{i-1}}^\varepsilon \right) - \text{sgn} \left( w_{t_{i}} - cz_{t_{i-1}} \right) \right].
\]

By the same argument as above we can find \( \varepsilon_{t_{i}} \leq \varepsilon_{t_{i-1}} \) such that (4.3) holds for \( \varepsilon \leq \varepsilon_{t_{i}} \).

Note that the finite union of exceptional sets, where the equalities (4.3) do not hold, has measure zero, and that there is no difficulty in modifying \( z \) in the way desired.

The result of the lemma is intuitively obvious in saying that for sufficiently small \( \varepsilon \) the process \( z^\varepsilon \) has on any finite interval paths that are identical with the paths of a modification of \( z \). (Note that the number of paths is finite.)

4.2. Lemma.

(4.4) \[ D_u \left[ F_{t_{i}}(w) \right] = V_x' \left( t_{i-1}, w_{t_{i-1}}; z_{t_{i-1}}, t_{i} \right) \int_{0}^{t_{i-1}} u_s ds \]

where \( \{u_s | s \geq 0\} \) has square integrable sample paths.

Proof. By Lemma 4.1, with \( \varepsilon \leq \varepsilon_{t_{i}} \),

\[
F_{t_{i}}(w + \varepsilon \int u_s ds) - F_{t_{i}}(w) = \text{erfc} \left( \frac{cz_{t_{i-1}} - w_{t_{i}}^\varepsilon}{\sqrt{4\pi(t_{i} - t_{i-1})}} \right)
- \text{erfc} \left( \frac{cz_{t_{i}-1} - w_{t_{i}}}{\sqrt{4\pi(t_{i} - t_{i-1})}} \right)
= V(t_{i-1}, w_{t_{i-1}}^\varepsilon; z_{t_{i-1}}, t_{i}) - V(t_{i-1}, w_{t_{i}}; z_{t_{i-1}}, t_{i}).
\]

Mean value theorem gives now

\[
= V_x' \left( t_{i-1}, w_{t_{i-1}} + \varepsilon \Theta \int_{0}^{t_{i-1}} u_s ds; z_{t_{i-1}}, t_{i} \right) \cdot \varepsilon \int_{0}^{t_{i-1}} u_s ds
\]

where \( 0 < \Theta < 1 \). Then it is immediate that

\[
\frac{1}{\varepsilon} \left( F_{t_{i}}(w + \varepsilon \int_{0}^{t_{i-1}} u_s ds) - F_{t_{i}}(w) \right) \to V_x' \left( t_{i-1}, w_{t_{i-1}}; z_{t_{i-1}}, t_{i} \right) \int_{0}^{t_{i-1}} u_s ds
\]
almost surely, as asserted.

4.3. Proposition. The functional $F_{t_i}(w)$ induces on $[-1, 1]$ a probability measure that is absolutely continuous with respect to the Lebesgue measure.

Proof. Set

$$u_s = V_x'(s, w_s; z_{t_j-1}, t_j) \quad \text{for} \quad s \in [t_{j-1}, t_j], \quad j = 0, \ldots, i.$$ 

Then the sample paths of $u = \{u_s \mid 0 \leq s \leq t_i-1\}$ are Lebesgue measurable and integrable as well as $F_x$-adapted. Also $D_u(D_u[F_{t_i}(w)])$ exists by an argument similar to that used in the proof of lemma 4.2.

But then

$$D_uF_{t_i}(w) = V_x'(t_{i-1}, w_{t_{i-1}}; z_{t_{i-1}}, t_i) \int_0^{t_i-1} u_s \, ds > 0$$

almost surely, since $V_x'(t_{i-1}, w_{t_{i-1}}; z_{t_{i-1}}, t_i) > 0$ for every $w$ as is seen by (3.11). Hence the probability law of $F_{t_i}(w)$ possesses a density by Theorem 5.2 of [12] (c.f. Proposition 2.3.1 in [16]).

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References


Luleå University of Technology
Department of Systems Engineering and Mathematics
S-951 87 Luleå
Sweden